# **Model 515 Flow Computer**

# **Operation Manual**

# **Application BF04**

Batch/Flow Controller for Mass Analog Flowmeters





22 December 2005

#### **Model 515 Flow Computer - Operation Manual**

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The information in this safety notice is for the prevention of injury to personnel and damage to the instrument.

The manufacturer assumes no liability for injury or damage caused by misuse of the instrument or for modifications made to the instrument.

#### **Qualified Personnel**

The instrument must be installed, operated and serviced by persons who have been properly trained and authorised. Personnel must read and understand this manual prior to installation and operation of the instrument.

#### **Static Hazard**

The 500 series flow computer uses high speed CMOS circuitry which is sensitive to static damage. The user should observe accepted safety practices for handling electronic devices, especially during servicing. Once the unit is installed, grounded and interconnected, the chances of static damage are greatly reduced.

#### Voltage Hazard

Before connecting power to the instrument, ensure that the supply voltage for the AC or DC input is suitable. The AC voltage rating is as stated on the serial number plate. Personnel should take all due care to avoid electric shock.

#### **Welding Hazard**

Do not perform electric welding in close proximity to the instrument or its interconnecting cables. If welding in these areas must be performed, disconnect all cables from the instrument. Failure to do so may result in damage to the unit.

#### **Moisture Hazard**

To avoid electrical faults and corrosion of the instrument, do not allow moisture to remain in contact with the instrument.

515 BF04 iii

iv 515 BF04

# **Contents**

1	Introduction	
	Features	1
	Overview	1
	Calculations	2
	Analog Input Scaling	2
	Displayed Information	
	Main Menu Variables	
	Communications	
	Isolated Outputs	3
	Relay Outputs	
	Software Configuration	3
	Approvals	4
2	Specifications	
	General	5
	Inputs	
	Outputs	
	Outputs	٠
3	Installation	
	Panel Mounting	7
	Electrical Connection	8
	Rear Panel Connections	8
	Terminal Designations	8
	Inputs	9
	Analog Input Connections	
	Logic Input Connection 1	(
	Outputs	
	4-20mA Output Connection 1	1
	Digital Output Connection 1	1
	Control Relays	2
	RC Network for Interference Suppression 1	
	Communications	3
	RS-232 Port	4
	Infra-red Port (Display Panel Option)	4
	RS-485 Port (Advanced Option)	4
	Earthing and Shielding	5
4	Operation	
-	Front Panel Operation	7
	Default Variable 1	
	Status Lamps	
	1	
	Front Panel Keys	C

515 BF04

Main Menu Items	 	 	 	 	 	 	18
Setting the Batch Preset	 	 	 	 	 	 	19
Setting the Flow Control Setpoint							20
Data Logs							
Model Information							22
Flow Control Modes							22
Local Flow Control Mode							22
Loop Flow Control Mode							23
Loop Tuning Mode							
Tuning the Control Loop							
Batch Control Modes							
Preset Mode							
On-Off Mode							
Release Mode							
Batch Control Operation							
Operation Configurations							
Starting a Batch							27
Stopping a Batch							
Resetting a Batch	 	 	 	 	 	 	28
Logic Input Control	 	 	 	 	 	 	28
Batch Errors	 	 	 	 	 	 	28
Batch Processes	 	 	 	 	 	 	29
5 Instrument Calibration Introduction	 	 	 	 	 	 	31
Calibration View Mode							31
Calibration Set Mode							
Changing the Instrument Settings							33
Calibration Menu Tree							34
Instrument Settings							
Units of Measurement							
Parameters							37
Inputs							41
Outputs							44
Alarms							47
Communications							48
Time Settings and Data Logging							50
General Setup Parameters							52
Test Menu							53
							54
System Messages							-
Error Messages							55
Warning Messages	 	 	 	 	 	 	55
6 Communications							
Overview	 	 	 	 	 		57
							57 57
Overview	 	 	 	 	 	 	

vi 515 BF04

Requests Format	60
Instrument Responses	61
Corrupted or Invalid Requests	64
Modbus RTU Protocol	65
List of Data Registers	66
Printer Protocol	71
Types of Printouts	71
Printer Data Control	74
ppendix A Glossary	
Glossary	77
ppendix B Model Numbers	
Product Codes	79
Custom Version Codes	
Application Information Code	
ppendix C Units of Measurement	
Available Units of Measurement	82
ndex	83

515 BF04 vii

viii 515 BF04

# **List of Figures**

1	500 Series Instrument Panel Mounting	7
2	Rear Panel Connections	8
3	Externally Powered Voltage Transmitter	9
4	Internally Powered Voltage Transmitter	9
5	Externally Powered Current Loop	10
6	Internally Powered Current Loops	10
7	Output 4-20mA Connection Diagram	11
8	Output Pulse Connection Diagram	12
9	External Relay Connection Diagram	13
10	RS-485 Interface Connections	15
11	Batch Operation with Manual or Automatic Reset	29
12	Batch Operation with Automatic Restart	30
13	Calibration Menu Tree Sheet 1	34
14	Calibration Menu Tree Sheet 2	35
15	RS-232 Cable Connections to a Computer	58
16	RS-485 Connections	58

515 BF04 ix

x 515 BF04

# Chapter 1 Introduction

#### **Features**

- Tailored for mass analog flow input
- Single or Dual stage control
- Preset or manual On-Off modes
- Easy access to batch and flow rate presets
- No-flow, leakage and overflow error detection
- Remote RUN/STOP/RESET
- Uses PI Loop Control
- Protection against Integral wind-up
- Allows for non-linear correction
- Storage of 1000 transactions with time and date stamp
- Selection of second language and user tags
- Infra-red communications port on front panel
- Pulse width and scaling of pulse output
- 4-20mA retransmission
- Selectable protocols on serial ports including Modbus RTU and Printer output
- Front panel adjustment of 8-24V DC output voltage
- Backlit display
- LCD backup

# **Overview**

The 515 BF04 application is a batching flow controller for delivery of preset quantities at preset flowrates using a mass analog input. Batch control can operate in preset or on-off modes, while flow control can be set to local (manual) or PI loop mode.

This application provides the operator with clear local readout including flowrate deviation and can be controlled via communications in more automated systems. There is quick access to commonly used preset values directly from the front panel if access has been authorized.

515 BF04

The PI control of the process flow is via a 4-20mA proportional valve or pump controller. It has integral wind-up protection, a deadband, output hold and ramp time that can be programmed to reduce wear on valves and actuators and provide for bumpless operation.

#### **Calculations**

To derive the flow rate, the analog input is normalised to a value (A) between 0 and 1.

 $massflow = (M_f max - M_f min)A + M_f min$ 

$$mass = \int (massflow \cdot \Delta t)$$

Automatic overrun compensation calculates the new valve closure point to ensure correct delivery by averageing the overrun amount from the last three complete batches.

The overrun compensation value is valid for a new preset value provided the stored overrun is less than 20% of the new preset.

# **Analog Input Scaling**

The analog inputs in this instrument are scaled by the following general formula:

$$f(A) = P_{min} + (P_{max} - P_{min}) \cdot A^*$$

where:

 $P_{min}$  = minimum point (equivalent to offset)

 $P_{max} = maximum point (P_{max} - P_{min} is equivalent to span)$ 

 $A^*$  = normalised signal (0 to 1) with correction applied for a flow input

#### **Correction Type**

• LINEAR:  $A^* = A$  when the instrument is not required to apply correction

• NON-LINEAR:  $A^* = A_C$  when the instrument applies correction from the points in the correction table

# **Displayed Information**

The front panel display shows the current values of the input variables and the results of the calculations.

The instrument can be supplied with a real-time clock for storage of up to 1000 transactions with time and date stamps.

#### Main Menu Variables

Main Menu Variables	Default Units	Variable Type
Mass	kg	Total
Mass Flowrate	kg/min	Rate
Process Control Output	%	Rate
Process Flowrate Deviation	%	Rate

Refer to **Available Units of Measurement** on page 82 for the list of available units.

#### **Communications**

There are three communication ports available as follows:

- RS-232 port (standard)
- RS-485 port (advanced option)
- Infra-red port (on front panel)

The ports are available for remote data reading, printouts and for initial application loading of the instrument.

# **Isolated Outputs**

The opto-isolated outputs can retransmit any main menu variable. The type of output is determined by the nature of the assigned variable. Totals are output as pulses and rates are output as 4-20mA signals. One output is standard, a second output is available as an option.

# **Relay Outputs**

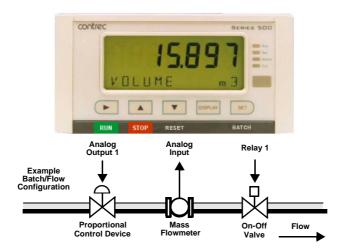
The relay outputs 1 and 2 are used to control the flow of product for each delivery. These contacts are normally open and can be used to drive external relays, valves, pump circuits etc. The advanced option provides another two relays that can be used as fully programable alarms for any rate type variable.

# **Software Configuration**

The instrument can be further tailored to suit specific application needs including units of measurement, custom tags, second language or access levels. A distributor can configure these requirements before delivery.

Instrument parameters including units of measurement can be programmed in the field, according to the user-access levels assigned to parameters by the distributor.

All set-up parameters, totals and logged data are stored in non-volatile memory with at least 30 years retention.



#### **Approvals**

This instrument conforms to the EMC-Directive of the Council of European Communities 89/336/EEC and the following standards:

- Generic Emission Standard EN 50081-1 Residential, Commercial & Light Industry Environment.
- Generic Emission Standard EN 50081-2 Industrial Environment.
- Generic Immunity Standard EN 50082-1 Residential, Commercial & Light Industry Environment.
- Generic Immunity Standard EN 50082-2 Industrial Environment.

In order to comply with these standards, the wiring instructions in **Chapter 3 - Installation** must be followed.

# Chapter 2 Specifications

## **General**

#### **Operating Environment**

**Temperature** -20°C to +60°C (conformal coating)

+5°C to +40°C (no coating)

**Humidity** 0 to 95% non condensing (conformal

coating)

5% to 85% non condensing (no coating)

**Power Supply** 95...135 V AC or 190...260 V AC or

12...28 V DC

Consumption Typically 6W

**Protection** Sealed to IP65 (Nema 4X) when panel

mounted

**Dimensions** 147mm (5.8") width

74mm (2.9") height 167mm (6.6") depth

**Display** 

Type Backlit LCD with 7-digit numeric display

and 11-character alphanumeric display

**Digits** 15.5mm (0.6") high **Characters** 6mm (0.24") high

**LCD Backup** Last data visible for 15min after power

down

Update Rate 0.3 second

#### Non-volatile Memory

Retention > 30 years

Data Stored Setup, Totals and Logs

**Approvals** 

Interference ( € compliance

**Enclosure** ATEX, FM, CSA and SAA approved

enclosures available for hazardous areas

Real Time Clock (Optional)

Battery Type 3 volts Lithium button cell (CR2032)

Battery Life 5 years (typical)

# Inputs

#### **Analog Input (General)**

**Overcurrent** 100 mA absolute maximum rating

Update Time < 1.0 sec

Configuration 4-20mA, 0-5V and 1-5V input

**Non-linearity** Up to 20 correction points (flow inputs)

4-20mA Input

**Impedance** 100 ohms (to common signal ground)

**Accuracy** 0.05% full scale (20°C)

0.1% (full temperature range, typical)

#### 0-5 or 1-5 Volts Input

**Impedance** 10Mohms (to common signal ground)

Accuracy 0.05% full scale (20°C)

0.1% (full temperature range, typical)

**Logic Inputs** 

Signal Type CMOS, TTL, open collector, reed switch

Overvoltage 30V maximum

# **Outputs**

#### **Relay Output**

No. of Outputs 2 relays plus 2 optional relays

**Voltage** 250 volts AC, 30 volts DC maximum

Current 3A maximum

#### **Communication Ports**

Ports RS-232 port

RS-485 port (optional)

Infra-red port

Baud Rate 2400 to 19200 baud Parity Odd, even or none

Stop Bits 1 or 2

**Protocols** ASCII, Modbus RTU, Printer (RS232)

#### **Transducer Supply**

**Voltage** 8 to 24 volts DC, programmable

**Current** 70mA @ 24V, 120mA @ 12V maximum

**Protection** Power limited output

#### **Isolated Output**

No. of Outputs 1 configurable output (plus 1 optional)

Configuration Pulse/Digital or 4-20 mA output

#### Pulse/Digital Output

Signal Type Open collector

**Switching** 200 mA, 30 volts DC maximum

**Saturation** 0.8 volts maximum

**Pulse Width** Programmable: 10, 20, 50, 100, 200 or

500ms

#### 4-20mA Output

**Supply** 9 to 30 volts DC external

**Resolution** 0.05% full scale

Accuracy 0.05% full scale (20°C)

0.1% (full temperature range, typical)

Important: Specifications are subject to change without notice.

# Chapter 3 Installation

# **Panel Mounting**

The instrument should be located in an area with a clean, dry atmosphere that is also relatively free of shock and vibration.

The standard mounting procedure is panel mounting in a cutout that is 139mm wide by 67mm high. Two side clips secure the unit into the panel.

Figure 1Figure 2 shows the panel mounting requirements for the 500 Series Instrument.

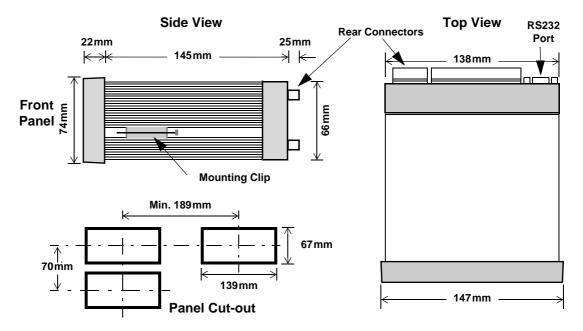


Figure 1 500 Series Instrument Panel Mounting

# **Electrical Connection**

#### **Rear Panel Connections**

Figure 2 shows the connections on the rear panel of the instrument.

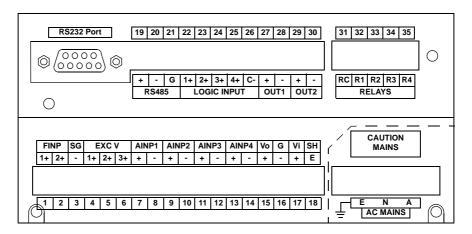


Figure 2 Rear Panel Connections

# **Terminal Designations**

Terminal Label		bel	Designation	Comment	Terminal Label			Designation	Comment
1	FINP	1+	Frequency Input 1+	Not used	19		+	RS485 (+)	
2	FINP	2+	Frequency Input 2+	Not used	20	RS485	-	RS485 (-)	Advanced option
3	SG	-	Signal ground		21		G	RS485 ground	
4	EXC V	1+	Excitation Term 1+	Not used	22		1+	Switch 1	Remote Run
5	EXC V	2+	Excitation Term 2+	Not used	23		2+	Switch 2	Remote Stop
6	EXC V	3+	Excitation Term 3+	Not used		LOGIC INPUTS	3+	Switch 3	Remote Reset
7	AINP1	+	Analog input ch 1 (+)	Not used 2			4+	Switch 4	
8	AINFI	-	Analog input ch 1 (-)				C-	Signal ground	
9	AINP2	+	Analog input ch 2 (+)	Not used	27	OUT 1	+	Output ch 1 (+)	Process control output
10	AINFZ	-	Analog input ch 2 (-)		28	0011	-	Output ch 1 (-)	Process control output
11	AINP3	+	Analog input ch 3 (+)	Main or low flow input	29	OUT 2	+	Output ch 2 (+)	Advanced option
12	AINES	-	Analog input ch 3 (-)	Main of low flow input	30	0012	-	Output ch 2 (-)	Advanced option
13	AINP4	+	Analog input ch 4 (+)	High flow stacked input	31		RC	Relay common	
14	AINF4	-	Analog input ch 4 (-)	riigii ilow stacked iliput	32		R1	Relay 1	Single Stage Control
15	Vo	+	8-24 volts DC output	Overload protected	33	RELAYS	R2	Relay 2	Dual Stage Control
16	G	-	DC Ground		34		R3	Relay 3	Advanced option
17	Vi	+	DC power input	DC power in 12-28V	35		R4	Relay 4	Advanced option
18	SH	Е	Shield terminal		RS	232 port	1	9-pin serial port	
Е		Е	Mains ground	10 10510511				ı	1
Ν	AC MAINS	Ν	Mains neutral	AC power in 95-135V or 190-260V					
Α		Α	Mains active						

# **Inputs**

## **Analog Input Connections**

All analog inputs can accept DC signals ranging from 0-5V, 1-5V and current signals from 4 to 20mA.

#### **CAUTION**

Applying levels of input current above the absolute maximum rating (100mA) may cause permanent damage to the input circuitry.

#### 0-5 and 1-5 Volt Inputs

For externally powered voltage transmitters, connect each transmitter to a pair of input terminals as shown in Figure 3. Refer to **Terminal Designations** on page 8 for specific terminal numbers for this application.

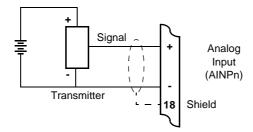


Figure 3 Externally Powered Voltage Transmitter

Connect internally powered voltage transmitters as shown in Figure 4.

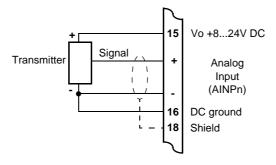


Figure 4 Internally Powered Voltage Transmitter

#### 4-20mA Inputs

For externally powered current loops, connect each transmitter to a pair of input terminals as shown in Figure 5. **Terminal Designations** on page 8 for specific terminal numbers for this application.

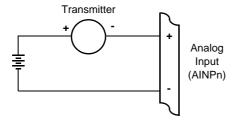


Figure 5 Externally Powered Current Loop

The internal overload-protected power supply has sufficient power for three current loops at 24 V DC (more current loops can be supplied by using a reduced voltage setting). Connect internally powered current loops as shown in Figure 6.

Transmitter

+ Analog Input (AINPn)

Analog Input (AINPn)

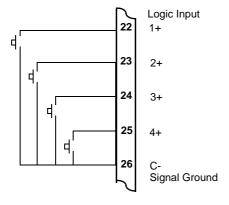
Figure 6 Internally Powered Current Loops

## **Logic Input Connection**

These inputs are designed to be connected to CMOS, TTL, open collector signals or a voltage free contact switch. A minimum activation time of 300mS is required to guarantee reading of an input.

It is possible to read the status of all the logic inputs via a Modbus register even if they are not used for a control purpose in the application.

A remote push-button key can be connected to the Logic Inputs as shown below. **Logic Input Control** on page 28 descibes the function of the inputs.



# **Outputs**

The advanced option for the instrument provides two opto-isolated output ports. Either or both can be used for 4-20mA or pulse outputs.

#### **CAUTION**

Due to the dual-purpose nature of the outputs, take care not to set the output as an open collector pulse type signal when connected to a 4-20mA loop circuit.

### 4-20mA Output Connection

Figure 7 shows the connections for a 4-20mA output. Output channel 1 uses terminals 27 (+) and 28 (-), output channel 2 uses terminals 29 (+) and 30 (-).

Maximum Load Resistance = (Supply-9) / 0.02 ohms

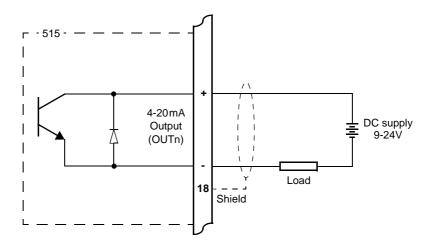


Figure 7 Output 4-20mA Connection Diagram

# **Digital Output Connection**

Figure 8 shows a connection example for a pulse output. Output channel 1 uses terminals 27 (+) and 28 (-). Output channel 2 uses terminals 29 (+) and 30 (-).

515 BF04

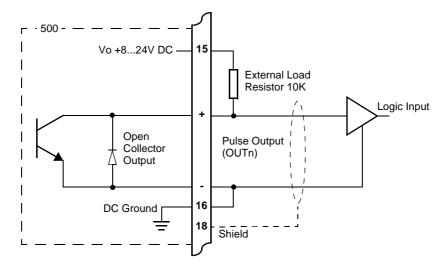


Figure 8 Output Pulse Connection Diagram

# **Control Relays**

The standard instrument has two relays, which are used for the dual stage batch control. The relays can drive external devices such as external relays, valves, pump circuits, lamps, and audible alarms. The operation of each relay can be set in calibration to determine at which points in the process the relays open or close. The advanced option has two extra relays that can be freely assigned as alarm relays.

There is also an equipment failure alarm option. This alarm has normally closed contacts which open when the instrument displays any error message as listed in **Error Messages** on page 55, or if there is a loss of power to the instrument.

The output characteristics of the relays are:

Maximum Voltage 30 volts DC or 250 volts AC

Maximum Current 3A

Figure 9 shows the connection of the relays.

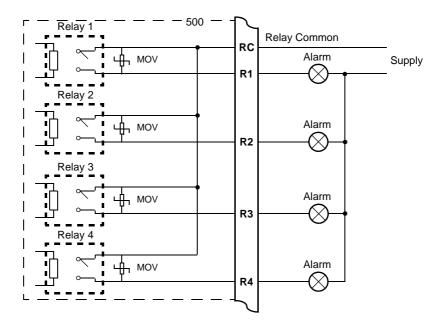


Figure 9 External Relay Connection Diagram

#### **RC Network for Interference Suppression**

When driving highly inductive loads with the relay outputs, it is recommended to use RC suppression networks (often called "Snubbers") for the following reasons:

- To limit the amount of electrical noise caused by arcing across the contacts, which may, in extreme cases, cause the microprocessor to act erratically.
- To protect the relay contacts against premature wear through pitting.

RC suppression networks consist of a capacitor and series resistor and are commonly available in the electrical industry. The values of R and C are dependent entirely on the load. However, if the user is unsure of the type of snubber to use, values of  $0.25\,\mu F$  and  $100\,\Omega$  will usually suffice. Note that only mains-approved RC suppression networks should be used.

The basic principle of the operation is that the capacitor prevents a series of sparks arcing across the contact as the contact breaks. The series resistor limits the current through the contact when the contact first makes.

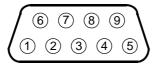
# **Communications**

The communication protocols are described in **Communications** on page 57.

515 BF04

#### RS-232 Port

The RS-232 port has a 9-pin DB female connector and has the following pinout:



Pin 1	Not used
Pin 2	Transmit (TxD)
Pin 3	Receive (RxD)
Pin 4	Not used
Pin 5	Ground
Pin 6	Not used
Pin 7	Handshake line (CTS)
Pin 8	RTS Out
Pin 9	Not used

**Note:** The instrument does not require a null-modem cable for connection to a personal computer. Refer to **Hardware Interconnection** on page 57 for cable termination requirements.

# Infra-red Port (Display Panel Option)

The infra-red port is located at the front panel, directly below the row of status indicators. The main function of this port is for retrieving current or logged data with a PC that has an infra-red port.

# RS-485 Port (Advanced Option)

Up to 32 units can be connected to a common RS-485 bus. Each unit has a unique address that the host computer uses to identify each instrument.

Figure 10 shows the connection of several instruments to a computer using the RS-485 port.

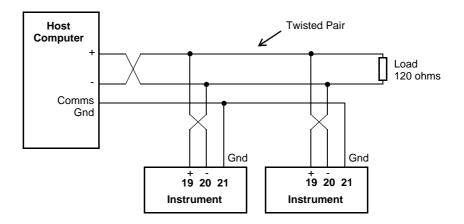


Figure 10 RS-485 Interface Connections

# **Earthing and Shielding**

It is a good practice to use shielded cable for all signal connections to the instrument. Care must be taken to separate signal cables from power cables to minimize interference.

Overall earth should be connected at the instrument end only. This connection should be as short as possible and connected to the earthing point on the rear terminal at pin 18.

# Chapter 4 Operation

# **Front Panel Operation**

This instrument is a batch computer that is capable of controlling the rate of flow during a delivery. Batch control can be via a Preset or an On-Off mode, while flow control can be via a Local (manual) or Loop (PI control) mode. The controller can be used in any combination of these modes to achieve the required functionality.

In normal operation, you press the buttons on the front panel to control the operation of the batch controller or to display the values recorded and calculated by the instrument.

There are several categories of information that the instrument can display:

- Totals
- Rates
- Batch preset values
- Flow control values
- Instrument settings

For each total, there is an associated rate as follows:

Total	Rate
Mass	Mass Flowrate

#### **Default Variable**

In some applications, a particular variable is of more interest than others, and for this reason a default variable can be assigned during instrument calibration. The default variable is used in the following ways:

- Determines what total the batch and preset is to be based upon.
- Determines what the display returns to if the display timeout option is enabled and no buttons are pressed for the selected period (usually 30 seconds). It also determines what is displayed on power up.

#### **Status Lamps**

The status lamps illuminate to show the following conditions:

Run
Set
Alarm
Cal

**Run** Solid led: The instrument has a batch in progress.

Flashing led: Fast, batch paused. Slow, waiting for valves to close.

**Set** Solid led: The instrument is in Calibrate Set mode.

Flashing led: Count down to automatic restart of next batch.

**Alarm** The instrument has an error, as indicated on the display panel.

**Cal** The instrument is in Calibrate View mode.

### **Front Panel Keys**

**RUN** Press the **RUN** key to start or resume a batch. The run led will illuminate.

Press the STOP key to halt a current batch. The instrument will go into pause mode and the run led will flash at a steady pace. The incomplete batch can be resumed. Also used to stop the next batch if in automatic restart count down.

Use the **RESET** key to clear the batch totals or to initiate a printout if the printer option has been selected. The print is activated with a single press while the reset of the totals requires a press and hold for two seconds.

The instrument makes three beeps when it resets the totals and two beeps when a printout is started.

**DISPLAY** Press the **DISPLAY** key to step or scroll through the main menu items.

Hold the BATCH key to display the current batch preset value. Continue to hold for two seconds to enter edit mode for the preset if access is authorised. Pressing the BATCH key briefly displays the accumulated total.

#### Main Menu Items

The main menu in this instrument consists of the following items. The DISPLAY key is used to step or scroll through the list. The full menu can only be viewed if the batch controller has been stopped and reset.

DISPLAY	Description	Options
MASS	Mass	Hold the SET key to display (or edit) the batch preset or briefly press to view the accum total
P-FLOW	Process flowrate	Hold the SET key to display (or edit) the controlling setpoint
P-CTRL	Process control output	Hold the SET key to display (or edit) the controlling setpoint

DISPLAY	Description	Options
DEVIAT	Process flowrate deviation	Hold the SET key to display (or edit) the controlling setpoint
REPORT PRINT	Only shown if print option is selected	Hold the SET key to print log report as defined in the TM/LOG section of calibration.
LOGGED DATA	Only shown if real-time clock option is installed	Hold the SET key to display data logs as described in <b>Data Logs</b> on page 20.
MODEL INFO		Hold the SET key to display the Model information as described in Model Information on page 22.
CAL MENU		Hold the SET key to enter Calibration View mode as described in Calibration View Mode on page 31.

#### **Setting the Batch Preset**



The batch preset can only be set while the instrument is in the non-operational state, i.e. batch is complete or has been stopped and reset. Hold the SET key to display the current preset value while viewing the total variable. The display of the preset will change from view mode to edit mode after 2 seconds if access has been enabled in calibration. Once in edit mode the Set indicator will illuminate and the preset value can be changed in the same way as in calibration set mode, see Changing Numeric Settings on page 33. The SET key is used to exit edit mode.

#### Limit on Batch Size

To prevent accidental entry of large batch quantities, a maximum batch limit can be programmed during calibration. The operator is then prevented from entering a batch quantity which exceeds this value.

#### **Common Preset Values**

If the batching application continually uses a regular set of preset values then quick access can be provided to these. In calibration, there is the opportunity to enter up to 10 commonly used preset values.

These can then be accessed whilst in batch edit mode (described above) by pressing the DISPLAY key. The pre-programmed values will appear in the order they were entered in calibration. The display will step through the presets back to the currently entered value which can still be manually edited. While displaying the desired preset value, press the SET key to accept the value and exit edit mode.

#### **Setting the Flow Control Setpoints**

SET

Hold the SET key to display (or edit) the controlling setpoint while viewing one of the "rate" variables. The display of the setpoint will change from view mode to edit mode after 2 seconds if access has been enabled in calibration. Edit mode can not be entered if a "Preset" batch is in progress. Once in edit mode the **Set** indicator will illuminate and the setpoint values are changed in exactly the same way as in calibration set mode.

#### **Data Logs**

The instrument will log up to 1000 deliveries (batches) if the real-time clock option is installed. The logs are taken at the end of each batch or upon reset if a batch has been aborted before the preset total has been reached. Each entry has a log number, a delivery number and a time and date stamp.

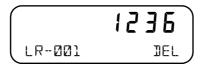
When the number of log entries exceeds 999 the oldest log entry is overwritten by the newest one.

#### **View Data Logs**

Use the following procedure to view the data that has been logged by the instrument:

- 1. Press the DISPLAY key to scroll through the menu to the LOGGE I INTH prompt.
- 2. Hold the SET key.

The system displays the most recent log record first. The log record number and corresponding delivery number are shown, for example LR-001 and DEL 1236.



- 3. Use the ▲ or ▼ keys to scroll to the delivery number or log record of interest.
- **4.** Press the DISPLAY key to show the information stored in the selected log record. Each log record consists of:
  - time and date stamp,
  - error code
  - totals for the delivery.
- **5.** While holding the DISPLAY key use the key to step through the stored information.

**6.** While holding the DISPLAY key use the RESET key to print the data for the displayed log if the printer option has been selected.

The following example shows the format of the time and date stamp at 15:25 (3:25 pm) on 16 January 2004. The day and month alternate with the year in the bottom right hand corner.

#### **Model Information**

The model information items display the hardware, software and application versions of the instrument. This information is mainly for service personnel.

DISPLAY	Description
-     -   -   -   -   -   -   -   -   -	The hardware model code. Refer to <b>Product Codes</b> on page 79 for more information.
L <b>H</b> 3604 INPUT	The Application number and the assignment of the inputs. Refer to <b>Application Information Code</b> on page 80 for more information.
0 10 1.002 3F04 VERS	The version of software loaded into the instrument.
026357 CUSTOM VERS	The Customer version code for this installation. Refer to <b>Custom Version Codes</b> on page 80 for more information.
123456 A3C123 5/N	The instrument serial number and unit tag. The serial number is on the top line and unit tag is on the bottom left. Both items are entered when the instrument application software is initially loaded. If the unit tag is not used the default tag, UNIT, will be used.
1 <b>6 - 15</b> EDITED 27/08 2002	The time and date when the calibration of the instrument was last edited. The format of the time and date is the same as for the data logs. This example shows 16:15 (4:15pm) on the 27th August 2002.
	This function is available only if the instrument has the real time clock option.

Press SET at any time to exit from the Model information.

# **Flow Control Modes**

This instrument can operate in the following flow control modes:

- Local (manual) mode
- Loop mode
- Tune mode (only available in calibration set mode)

#### **Local Flow Control Mode**

The desired process control output (P-CTRL %) is manually set via the front panel or serial communications.

The output signal is used to control a proportional control valve or variable speed drive to obtain the desired flow. In this mode the flow deviation (DEVIAT %) is set to zero.

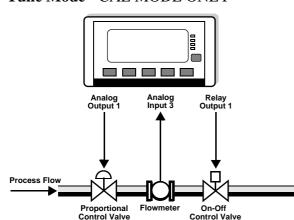
#### **Loop Flow Control Mode**

The desired process flowrate set point (P-FLOW SP) is set via the front panel or serial communications.

The PI controlled output signal is used to maintain the desired process flowrate via a proportional control valve or variable speed drive.

# **Loop Tuning Mode**

Tune Mode - CAL MODE ONLY



This mode is only accessed from within calibration mode and allows the operator to view a concise list of key parameters and gain immediate feed back. The Proportional Band (P-BAND) and Integral Time (I-TIME) are entered to tune the system.

For details on this method see below: "Tuning the Control Loop".

The **RELEASE** prompt in batch mode is used to open the On-Off control valve from within calibration.

# **Tuning the Control Loop**

The Process Controller has a special control mode, within the Parameters section of calibration, to assist in tuning the control loop. This mode provides a concise list of key parameters and allows for immediate feedback. The basic principle in tuning the loop is to gradually adjust the Proportional Band (P-BAND) and the Integral Time (I-TIME) and observe the response to a step change in the setpoint.

The tune menu provides for this by allowing the P-BAND and I-TIME to be programmed and then a Process Flow (P-FLOW) setpoint value to be entered. The next items in the menu are the actual live process variable and the deviation from the target value, so that the response of the system to a setpoint change can be observed. Unless the menu is quit the program will step back to start of the tuning menu so that new values of P-BAND and I-TIME can be entered and the effect of a step change in the setpoint be monitored.

As the idle position for any On-Off control valve in a batching system is "closed", a special option in the Batch Mode parameter, RELEASE, allows the valve to be opened from within calibration. For more information, refer to **Release Mode** on page 25.

This sequence is used for Loop mode. The tuning procedure is as follows:

- **1.** Before tuning the control loop it is essential to program in the correct parameters for the flowmeters, including filtering.
- **2.** The actual Process Flow Range (P-FLOW RANGE) should be measured and entered. It is determined by setting the Control Mode to LOCAL, Batch Mode to RELEASE, setting the *Flow Setpoint* (control output) to 100% (20mA) and then observing the steady state flowrate.
- **3.** With the correct Process Flow Range entered and Batch Mode still set to RELEASE the Control Mode should now be set to LOOP to continue the tuning procedure.
- **4.** With the Loop Error Deadband (D-BAND) and the Output Ramp Time (R-TIME) set at zero, the I-TIME should be set to zero (disabled) and the P-BAND set at 150%.
  - Gradually decrease the P-BAND value until the system begins to oscillate when a small step change of the setpoint is introduced. When this occurs, double the value of the P-BAND.
- **5.** Next set the I-TIME to 20 seconds and gradually decrease the value until the system again begins to oscillate when a small step change of the setpoint is introduced. When this occurs double the value of the I-TIME.
- **6.** The Deadband and the Output Ramp Time can now be programmed as required.

The system should be tuned around the flowrate at which the eventual system will operate. The stability of the loop should then be checked at various flowrates and setpoints.

# **Batch Control Modes**

This instrument can operate in the following Batch control modes:

- Preset mode
- On-Off mode
- Release mode (only available in calibration set mode)

#### **Preset Mode**

If the batch mode is **PRESET** the prestop and shut-off points are determined by the instrument.

The instrument can be set to count up from zero or down from the preset value. A slow flow start feature and reduction of flowrate when approaching the desired quantity is available for smoother batching. The automatic overrun compensation feature can be used to improve accuracy and repeatability. An auto-restart feature for automated repeat batches is also available in preset mode.

#### **On-Off Mode**

If the batch mode is **ON-OFF** the shut-off point is determined by the operator.

The instrument will operate in a count up direction. The slow flow start feature can still be used, but in this mode starting and stopping is determined by the operator and in this mode there is no End of batch output signal.

#### Release Mode

The **RELEASE** prompt in batch mode is used to open the On-Off control valve from within calibration, primarily for tuning and commissioning purposes.

The RUN led is illuminated while the On-Off valve is "open". The type of flow control while the valve is open is dependent on the control mode at the time. If in LOOP mode PI Loop flow control is activated.

For PI Loop tuning procedures that may need the flow to be "released" for a considerable time it is important that the flow is directed to an appropriately sized vessel.

If calibration is exited while in Release mode the On-Off valve will close and the batch mode will default to Preset mode.

# **Batch Control Operation**

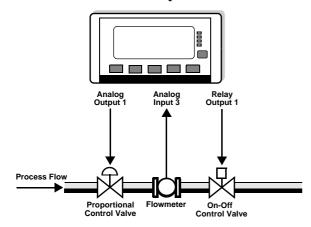
### **Operation Configurations**

For batch control this instrument can be used in three main configurations:

- Config 1. Using flow control output plus 1 control relay
- Config 2. Using flow control output only (no relays)
- Config 3. Using 2 control relays (no flow control)

#### **Configuration 1**

#### Flow Control & 1 Relay



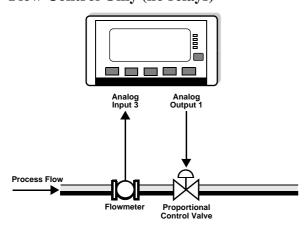
The Hold Output feature can be used in this configuration to provide a faster return to the desired flowrate when the next batch is started.

The analog flow control output can be used to operate either a proportional control valve or a variable speed drive.

The On-Off control value allows the system to achieve high accuracy batching.

#### **Configuration 2**

#### Flow Control Only (no relays)

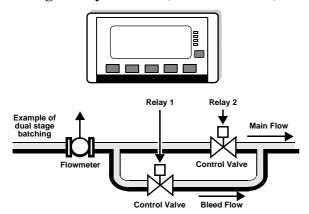


The Hold Output feature must be disabled in this configuration as the system relies on the proportional control valve to completely stop the flow.

While this system uses less hardware it is not recommended when high accuracy batching is required.

#### **Configuration 3**

#### 2-Stage Relay Control (no flow control)



The batch controller can still be used in a conventional dual stage configuration. The Control Mode should be set to Local and the analog flow control output remains unused.

Parameters for slow start and prestop points are provided to control the operation of Relay 2.

A digital output can be programmed as a pump control signal if required.

# Starting a Batch

To start the process the **RUN** key is pressed. The RUN led will illuminate and the instrument will begin to totalise from zero or, if programmed for Preset and count down mode, the display will decrement from the preset quantity.

The batch controller's analog ouput and two relays can be used to control the delivery of product. These are energised and de-energised as described below.

# Stopping a Batch

The process can be stopped at any time by pressing the STOP key. Once the process has been interrupted in this way it can be continued by pressing the RUN key or the batch can be aborted and the instrument reset by pressing the RESET key.

When the process is interrupted it is in pause mode and the RUN led will flash to prompt the operator to restart or abort the batch.

# Resetting a Batch

The instrument can be programmed to reset by different means.

- At the end of a batch, the **RESET** must be pressed to reset the batch total. If the instrument is programmed to count down, the display will revert to the preset value. If it is programmed to count up or is operating in On-Off mode, the batch total will clear to zero. The next batch can not be started until the previous batch total has been reset.
- If Auto Reset is enabled in the parameters section of calibration, the batch total will automatically reset when the RUN key is pressed for the start of the next delivery.

# **Logic Input Control**

This instrument allows for remote operation via the logic inputs on the rear terminals. The logic input have the following functions:

- Logic Input 1 Remote Run
- Logic Input 2 Remote Stop
- Logic Input 3 Remote Reset

For connection details, refer to **Logic Input Connection** on page 10.

#### **Batch Errors**

The instrument has the ability to raise an alarm when it detects a loss of flow, an overflow or a leakage in the system.

- **No Flow Error** The no flow condition is detected when the flow timeout expires during a delivery. There must not be a period of no flow greater than the timeout value during the delivery.
- Overflow Error The overflow condition is detected when the flow continues longer than the timeout period after the controller has attempted to stop the flow.
- **Leakage Error** The leakage condition is detected when an amount greater than the acceptable total is received without flow being initiated by the batch controller.

The point at which these errors are detected is dependant on the values programmed into the calibration parameters Batch Flow Timeout and Acceptable Total. The open collector outputs can be assigned to activate whenever one of the flow errors occur. Refer to **Instrument Settings** on page 36 for more details.

#### **Batch Processes**

The batch controller can be programmed during calibration to operate in various ways including:

- Manual Reset (manual start).
- Automatic Reset (manual start).
- Automatic Restart for continuous batches (Preset Mode only).

In each of the above modes and configurations the parameters can be programmed to determine the behaviour and timing of relays and output signals. The following figures provide examples of some batch operations. Refer to **Instrument Settings** on page 36 for more details.

#### **Manual and Automatic Reset**

If Manual Reset the **RESET** key must be pressed at the end of the batch to clear the batch total. This must be done before another batch can be started. If Automatic Reset is programmed, a new batch is commenced each time the **RUN** key is pressed.

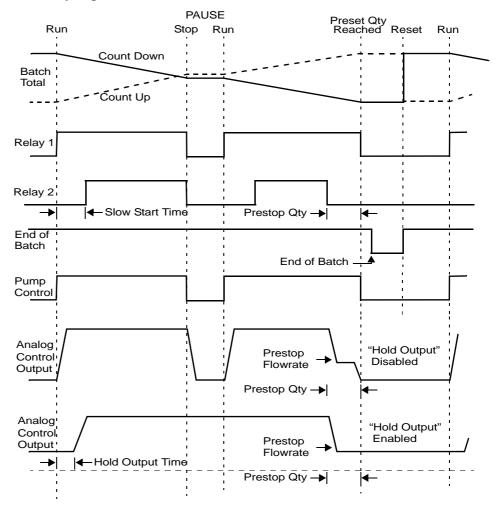


Figure 11 Batch Operation with Manual or Automatic Reset

#### **Automatic Restart**

If Automatic Restart is enabled the next batch will commence automatically when the restart timer expires after the end of batch has occurred. The SET led will flash while the instrument is waiting to automatically restart.

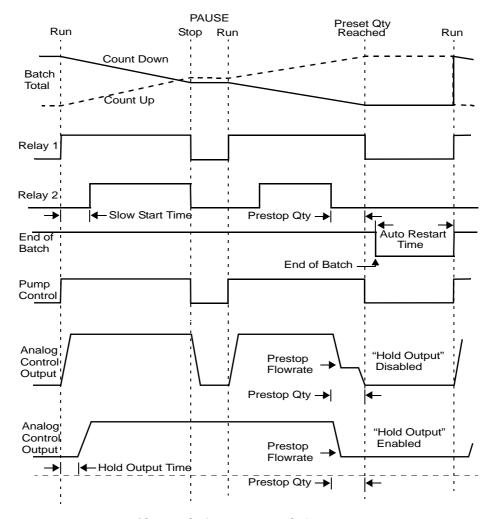


Figure 12 Batch Operation with Automatic Restart

# **Chapter 5 Instrument Calibration**

# Introduction

You can view or change the settings of the instrument according to the access level for each parameter as set by the manufacturer. There are four levels of access to the parameters as follows:

- **Not visible** you cannot display or edit the parameter.
- **Display Only** you can display the parameter, but you cannot change the setting.
- **Programmable** you can change the setting of the parameter in Calibration Set mode.
- **Password protected** you can change the setting of the parameter in Calibration Set mode only if you enter the correct password.

**Note:** When you enter Calibration Set mode, the instrument requests you to enter a password. You can enter any "incorrect" password to change the settings of the "programmable" parameters. You must enter the correct password to change the password-protected parameters.

# **Calibration View Mode**

Use the following procedure to view the calibration settings of the instrument:

- 1. Press DISPLAY to scroll to the EAL MENLI prompt.
- 2. Hold the SET key.



The instrument beeps once, illuminates the **Cal** indicator and shows **EAL** on the display panel.

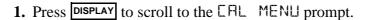
- Press **•** to scroll through the flashing menu headings.
- Press SET to scroll through submenu items.
- Press DISPLAY to return to the main calibration menu.
- **3.** To exit from the Calibration View mode, press to scroll to the END option and press SET).

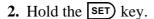
The instrument returns to Normal Operation mode.

# **Calibration Set Mode**

In Calibration Set mode, you can change the settings of the "programmable" parameters. You must enter the system password to change the setting of the "password-protected" parameters.

Use the following procedure to enter Calibration Set mode:







The instrument beeps once, illuminates the **Cal** indicator and shows **EFL** on the display panel.

- 3. Press to select any flashing menu heading except ENI.
- **4.** Hold **SET**) for two seconds.

The instrument requests a password.

- 5. Press ▲ or ▼ to change the value of the current digit. To select the next digit, press ▶.
- **6.** Press **SET** to accept the password.
  - The instrument makes two beeps for a correct password entry and enables you to change the "programmable" and "password-protected" parameters.
  - The instrument makes one beep for an incorrect password entry and enables you to change only the "programmable" parameters.

Run Set Alarm

The instrument illuminates both the **Cal** and **Set** indicators.

- **7.** Edit the instrument parameters as required. The programmable values are indicated by the flashing display.
  - To change a numerical value, press ▲ to increase a value, or press ▼ to decrease a value. Press a key momentarily to change the value one number at a time. Hold a key to scroll through the numbers. To proceed to next digit, press ▶.
- **8.** Press **SET** to accept the currently displayed value and proceed to the next parameter. You can press **DISPLAY** to return to the main calibration menu.
- 9. To exit from Calibrate Set mode, press to scroll through the main calibration menu to ENII, then press SET. Otherwise, from any menu, you can press and hold SET for two seconds.

Run
Set
Alarm
Cal

The instrument makes two beeps and cancels the **Cal** and **Set** indicators.

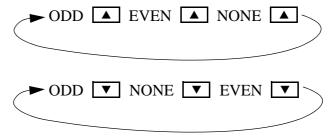
# **Changing the Instrument Settings**

In Calibration Set mode, the display flashes the item that can be changed. For option settings, the display flashes the complete option. For a numeric parameter, the display flashes one digit at a time, you can change the value of the flashing digit as required, then move the flashing cursor to change another digit.

**Note:** When you change the setting of a parameter, the instrument records the result as soon as you move to another parameter, or exit from the Calibration Set mode.

### **Changing Option Settings**

When you display an option that can be changed, the entire option flashes on the display, such as the choices of ODD, EVEN or NONE for the communications parity bit checking. Press or to change the option. You can "scroll" through the options in either direction to make a selection as shown below.



#### **Changing Numeric Settings**

The display flashes the digit that can be changed.

Press to select the digit that you wish to change.

Press ▲ or ▼ to increase or decrease the value of the selected digit.

#### **Changing the Decimal Point**

To change the position of the decimal point, press ▶ to move the flashing selection until the decimal point flashes. Press ▲ or ▼ to move the decimal point to the right or left as required.

#### **Units of Measurement**

The calibration of some parameters is based on the units that are defined for the relevant variables. These units of measurement can been viewed in the UNITS menu in calibration below.

## **Calibration Menu Tree**

Figure 13 and Figure 14 show the keys for moving around the calibration menu tree in Calibration View or Set mode.

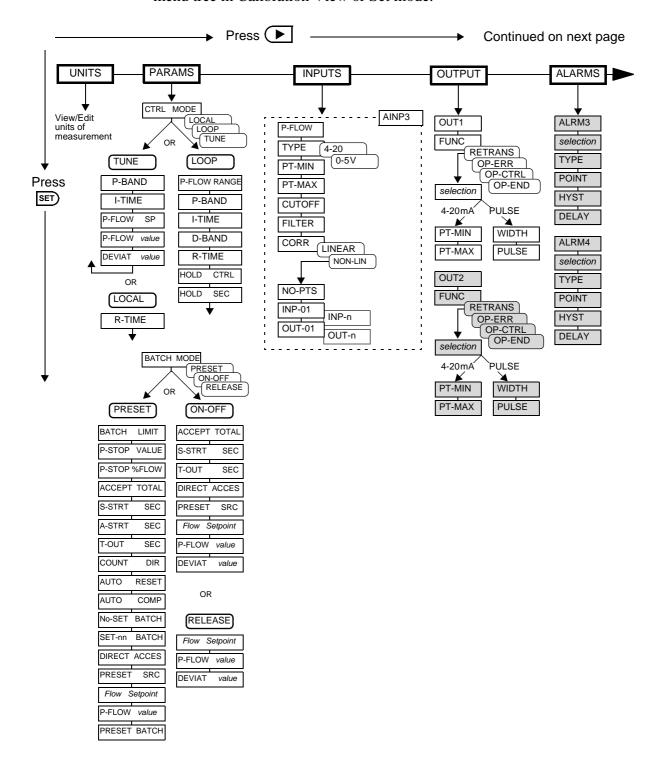


Figure 13 Calibration Menu Tree Sheet 1

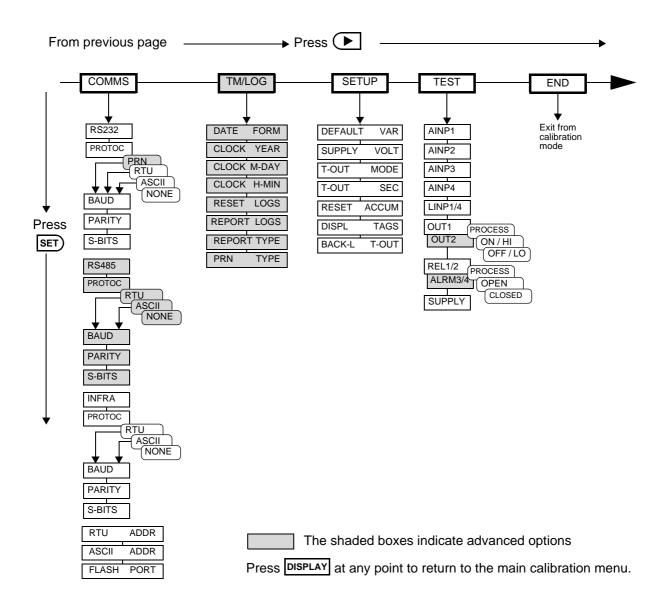


Figure 14 Calibration Menu Tree Sheet 2

# **Instrument Settings**

# **Units of Measurement**

The Units menu allows the units to be viewed and edited if necessary without the reloading of new application software. Any change in units will result in a full reset to initially downloaded settings. Therefore, any required changes to units of measurement should be made before changing any other settings.

SET ↓	igoplus  o UNITS params inputs outputs alarms comms tm/log setup test end	
ITEM n unit	The units for main menu or calibration items can be viewed by pressing the SET key.	
	The units of measurement are password protected. To edit the units the correct password must be entered on entry to EDIT mode.	
	Press or to select the required units. Refer to Available Units of Measurement on page 82 for the list of available units.	
ACCEPT UNITS	The Accept Units prompt will only appear if one or more of the units have been changed.	
	<b>IMPORTANT:</b> Accepting the change of units will initiate a master reset. All calibration parameters will revert to their default value (i.e. those values included in the downloaded instrument software). All totals and any logged information will be cleared.	
	Press or to select YES, then press the set key. The instrument makes three beeps to confirm the reset command.	
	The message -RESET- PLEASE WAIT will be displayed as the instrument exits calibration mode and completes a full re-boot sequence.	

# **Parameters**

SET) ↓	$ ightarrow$ units $ m {\bf PARAMS}$ inputs outputs alarms comms tm/log setup test end
CTRL MOJE	Select the required loop control mode.
	<ul> <li>LOCAL - Manual control operating mode.</li> <li>LOOP - PI loop control operating mode.</li> <li>TUNE - PI loop control tuning mode.</li> </ul>
	Press ▲ or ▼ to select either: LOCAL, LOOP or TUNE.
	Refer to the section Control Modes for descriptions of each mode.
CONTROL MOD	ntrol items actually shown in the PARAMS menu are dependent on the E chosen above. Items that are not relevant for that mode will not appear. In Menu Tree as a guide to the relevant items.
P-FLOW RANGE	The process or loop flow range is the maximum flowrate that the system will achieve on the process flow line. This value is used by the loop control algorithm and is entered in the same units as the main menu Process Flowrate variable. It can be determined by setting the process control setpoint to 100% whilst in LOCAL mode and observing the flowrate.
K ENRE-9	The proportional band of PI control algorithm.
	Enter the value in percentage. For means of determining this value see  Tuning the Control Loop on page 23.
I-TIME SEC	The loop integral time of PI control algorithm. This parameter should be programmed as a non-zero value to enable the integral term in the control algorithm.
	Enter the value in seconds. For means of determining this value see <b>Tuning the Control Loop</b> on page 23.
Z CORE-C	The loop error deadband can be programmed to prevent the output continuously changing and thereby reducing wear on valves and actuators. Enter the value as a percentage.
	While the main menu Deviation Percentage (error) is within the deadband, the process control signal will remain steady (i.e. the error is treated as zero in the algorithm).
R-TIME SEC	The ramp time limits the rate of change of the loop output signal and assists in bumpless loop operation when changing operation mode or loop parameters. It represents the minimum time required for the output signal to traverse between saturation points (i.e. from 0 to 100% or vice versa).

SET ↓		lacktriangledown units $PARAMS$ inputs outputs alarms comms tm/log setup test end	
HOLI	ETRL	The hold control output feature leaves the output signal at its last value a the end of a batch (flow should be stopped by the on-off valve).	
		This allows the control actuator to start a new batch without ramping up from a fully closed position.	
		Press or voto select ENABLE or DISABLE.	
HOLI	SEC	The hold control output time determines when the loop control takes over after a batch starts or resumes. This can provide time for the on-off valve to open and flow to reach a stable flowrate before the systems resumes loop control.	
BATCH	MOJE	Select the required batch control mode.	
		• PRESET - Preset delivery.	
		• <b>ON-OFF</b> - Manual delivery.	
		• <b>RELEASE</b> - Release flow (loop tuning, only available in calibration mode).	
		Press • or • to select either: PRESET, ON-OFF or RELEASE.	
		Refer to the section Batch Modes for descriptions of each mode.	
BATCH	MODE cl	ontrol items actually shown in the PARAMS menu are dependent on the nosen above. Items that are not relevant for that mode will not appear. Use the Tree as a guide to the relevant items.	
ВЯТСН	LIMIT	The batch limit determines the maximum batch preset value that can be entered. If a value of zero is entered for this parameter then no limit is applied.	
		Enter the value in the engineering units of the batch preset.	
P-STOP	VALUE	The prestop value determines when relay 2 deactivates and the control output reduces as the batch approaches the preset quantity.	
		Enter the value in the engineering units of the batch preset.	
P-STOP	%FLOW	The batch prestop flowrate is programmed as a percentage of the loop/process flowrate setpoint and is used to slow the flow during the prestop stage of batching.	

SET) ↓		igodellar $ ightarrow$ units $PARAMS$ inputs outputs alarms comms tm/log setup test end	
ACCEPT	TOTAL	The acceptable batch total determines when a leakage error is raised. An error is detected if an amount greater than the acceptable total is received without flow being initiated by the batch controller. It also allows small totals due "meter skips" and vibration to be discarded without being considered as a valid delivery.	
		Enter the value in the engineering units of the batch preset.	
S-STRT	SEC	The batch slow start time determines when relay 2 activates after the start or resumption of a batch.	
		Enter the value in seconds.	
A-STRT	SEC	The batch automatic restart time determines the time that will elapse between the end of one batch and the start of the next. A value of zero disables the auto restart feature.	
		Enter the value in seconds.	
T-OUT	SEC	The batch flow timeout determines length of no flow time that the instrument will wait during a batch before raising a no flow error. It is also determines when an overflow error is raised if flow does not cease within the timeout period after the controller attempts to stop the flow. A value of zero disables these flow timeout features.	
		Enter the value in seconds.	
COUNT	IIR	The batch count direction determines whether the batch total counts up from zero to the preset value or down from the preset to zero.	
		Press ▲ or ▼ to select UP or DOWN.	
яито	RESET	This parameter is available for viewing and editing only when the batch automatic restart time is set to zero.	
		The automatic reset feature allows the previous batch total to be reset automatically when a new batch is started with the RUN key.	
		Press or vo select ENABLE or DISABLE.	

SET) ↓	igoplus  o units $PARAMS$ inputs outputs alarms comms tm/log setup test end
AUTO COMP	The batch automatic overrun compensation allows the instrument to automatically compensate for any consistent overrun at the end of the batch. Overrun is typically due to the slowness of a valve to close or a pump to stop on receiving a signal from the batch controller and results in the delivered quantity being greater than the entered preset
	In calculating the amount to be compensated for the instrument uses the average overrun from the last three batches. An overrun of more than 20% is considered invalid and will not be included in the calculations.
	Press ▲ or ▼ to select ENABLE or DISABLE.
No-SET BATCH	To provide faster access to commonly used preset values a number of batch presets can be preprogrammed into the instrument. This parameter allows the number of batch presets to be entered.
	Press ▲ or ▼ to select a number between 1 and 10.
SET-01 BATCH to SET-n	Enter the commonly used preset values for quick access via the front panel.
	Enter the value in the engineering units of the batch preset.
DIRECT ACCES	If the direct access is enabled then the operator is able to enter edit mode for the preset parameters (batch and flow) directly from the main menu by holding the SET key while viewing the preset. If disabled the presets can only be changed from within calibration set mode (or via serial communications, see below). Select the direct access mode as required.  Press  or to select ENABLE or DISABLE.
PRESET SRC	The instrument allows the batch and flow preset value to be changed via either of two methods:
	<ul> <li>USER - The instrument allows the preset values to be changed only by the user via the front panel.</li> <li>RTU - The instrument allows the preset values to be changed via Modbus RTU communications or by the user via the front panel.</li> </ul>
	Press ▲ or ▼ to select USER or RTU.
P-CTRL SP	Preset process control signal setpoint. This setpoint is only available for LOCAL control mode.
	Enter the value in the engineering units of the assigned variable.
	mode the live P-FLOW value is now shown to give immediate feedback libration set mode.

SET	L	lacktriangledown units $PARAMS$ inputs outputs alarms comms tm/log setup test end	
P-FLOW	5P	Preset Loop/Process flowrate setpoint. This setpoint is only available for LOOP control and TUNE modes. The value of the setpoint must not be greater than the process flow range (P-FLOW RANGE).	
	If LOOP control or TUNE mode the live P-FLOW and DEVIATION values are now shown to give immediate feedback without leaving calibration set mode.		
PRESET I	8ЯТСН	Enter the batch preset quantity. This setpoint is only available for PRESET batch mode.	
		Enter the value in the engineering units of the assigned variable.	

# Inputs

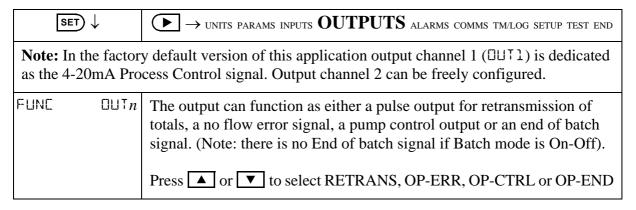
SET	) <b>\</b>	igwedge $ ightarrow$ units params $f INPUTS$ outputs alarms comms tm/log setup test end
Analog Input 3 & 4		
P-FLOW	RINP3 RINP4	For this application Analog Input Channels 3 is assigned to process flowrate main input (if not stacked) or low range is stacked with Analog Input Channel 4.
TYPE	EQNIR PQNIR	Select the type of analog input source.  Press ▲ or ▼ to select 0-5 V, 1-5 V or 4-20 mA.
PT-MIN PT-MAX	EQNIR PQNIR	Enter the value of the measured parameter (in the defined engineering units) that corresponds to the minimum input signal level. The minimum point is commonly set at a base flowrate of 0.0.  Enter the value of the measured parameter (in the defined engineering units) that corresponds to the maximum input signal level. The maximum point is the same as the base value (set at the minimum point) plus the span value.  For example, if the source signal is 4mA at a minimum massflowrate of 2kg/M, enter 2 as the minimum point. If the source signal is 20mA at a maximum massflowrate of 250kg/M, enter 250 as the maximum point.
CUTOFF	EQNIA PQNIA	The Cut-off is the lowest value that the instrument reads from the input sensor. The cut-off setting is the percentage of the span of the input values.  All inputs at or below the cut-off value are considered negligible to the instrument and are ignored. In this case, the instrument uses the minimum value (set at PT-MIN).

SET) ↓		ightarrow units params $ m INPUTS$ outputs alarms comms tm/log setup test end			
FILTER	Equip Pquip Pquip	Input fluctuations caused by pulsating flow tend to create distortion in the input readings of the rate. The instrument has a digital filter that averages out these fluctuations.  As a guide to the degree of filtering to use, the following table shows the response time (in seconds) to reach 90% and 99% of a step change in input.  The value A is the filter constant that the user can set.			
		Filter setting A	Seconds to reach 90% of full swing	Seconds to reach 99% of full swing	
		0	0	0	
		2	2	4	
		4	4	8	
		6	5	10	
		10	8	15	
		15	12	23	
		20	14	27	
		25	18	34	
		35	25	48	
		45	32	62	
		60	42	82	
		75	52	102	
		90	62	122	
		99	68	134	
		The input filter range is there is no filtering.	from 0 to 99. A setting of	of 0 (zero) means that	
CORR	RINP3 PINP4	<ul><li>LINEAR</li><li>NON-LINEAR to us</li></ul>	rity can be corrected as for se the following linearity ect LINEAR or NON-LIN	correction parameters	

SET) ↓		lacktriangledown units params $INPUTS$ outputs alarms comms tm/log setup test end	
	EPNI PPNI	This parameter is available for viewing and editing only when the correction type is set to Non-linear.	
		Enter the number of non-linearity correction points.	
		Press or to select a number between 1 and 20 for the number of correction points.	
	INP3 INP4	This parameter is available for viewing and editing only when the correction type is set to Non-linear.	
		Enter the normalised input value for the correction point.	
		The instrument uses linear interpolation between the correction points. An input and an output value are entered for each correction point. The values are normalised between the minimum point (0.0) and the maximum point (1.0). Only the points between 0 and 1 are required to be entered and should be entered in ascending order.	
		The following diagram shows a 5 point linearised representation of the input for a hypothetical flowmeter. The heavy black line represents the actual input from the flowmeter. The light black line is the approximation that the instrument uses.	
		Normalised Output 1.0	
		OUT-05	
		OUT-01 Normalised	
		0.0 INP-01 INP-02 INP-03 INP-04 INP-05 1.0 Value	
		You can press the DISPLAY key to skip the non-linear points and go to the next item.	
OUT-01 A: to OUT-n	INP3	This parameter is available for viewing and editing only when the correction type is set to Non-linear.	
		Enter the normalised output value for the correction point.	

SET) ↓	$ ightharpoonup$ units params $\overline{ ext{INPUTS}}$ outputs alarms comms tm/log setup test end
	Select YES to stack AINP3 as the low range input with AINP4 as the high range input.  Select NO to use AINP3 as the only flow input.
SW-LO RINP3 SW-HI	Select NO to use AINP3 as the only flow input.  These parameters are available for viewing and editing only when the Stack option is set to Yes.  Stacked DP switching is based on the low-range input (AINP3). When the input is less than the SW-LO value, the instrument switches to the low-range input (AINP3). When the input is greater than the SW-HI value, the instrument switches to the high-range input (AINP4).  The switch settings are percentages of the span of the unadjusted input to AINP3. For example, with a 4-20mA input, a setting of 90% is 18.4mA and 95% is 19.2mA. $\frac{(20-4)\times 90}{100} + 4 = 18.4 \qquad \frac{(20-4)\times 95}{100} + 4 = 19.2$ Enter SW-LO and SW-HI values as 0 to 99%. SW-HI should be set sufficiently higher than SW-LO to avoid rapid toggling between the two inputs.

## **Outputs**



SET) ↓	$ ightharpoonup$ units params inputs ${f OUTPUTS}$ alarms comms tm/log setup test end	
PULSE DUT or 4-20	You can assign any of the "main menu" variables to an output. The nature of the output depends on the assigned variable. Totals are output as pulses and rates are output as 4-20mA passive signals.	
	Press or to select the variable that is required as an output. The top of the display shows the type of output signal that is assigned to the variable.	
	CAUTION	
	Due to the dual-purpose nature of the outputs, take care not to set the output as an open collector pulse type signal when connected to a 4-20mA loop circuit.	
וטס אדעוש	The Output Pulse Width is available for viewing and editing only when the assigned variable is a total (pulse output) type.	
	Pulse output is usually used to drive remote counters. Set the pulse width (in milliseconds) as required by the remote counter.	
	Press ▲ or ▼ to set to: 10, 20, 50, 100, 200 or 500 ms.	
PULSE OUT	The Output Pulse Factor is available for viewing and editing only when the assigned variable is a total (pulse output) type.	
	The Output Pulse Factor is the scaling factor for the retransmission of the measured total quantity.	
	For example, if "volume" is chosen as an output variable, the engineering unit is cubic metres. Therefore a pulse factor of 1.000 generates one pulse for 1 m <sup>3</sup> . Similarly, a pulse factor of 3.000 generates one pulse for 3 m <sup>3</sup> .	
	For more information, see <b>Output Pulse Factor</b> on page 46.	
	The output pulse factor cannot be 0 (zero).	

SET) ↓	lacktriangledown units params inputs $f OUTPUTS$ alarms comms tm/log setup test end
PT-MIN OUT PT-MAX OUT	
	The output minimum value corresponds to the 4mA point and the output maximum value corresponds to the 20mA point.
	Setting the output range differently from the input range enables the instrument to amplify the input signal. You can drive a chart recorder that "zooms in" on a specified range of values instead of displaying the full operating range of the transducer.
	For example, if the minimum point is set to $30\mathrm{m}^3/\mathrm{min}$ and the maximum point is set to $100\mathrm{m}^3/\mathrm{min}$ , the 4 to $20\mathrm{mA}$ range would reflect the volumetric flow rate range of 30 to $100\mathrm{m}^3/\mathrm{min}$ . At rates above the maximum and below the minimum points, the output remains at $20\mathrm{mA}$ and $4\mathrm{mA}$ respectively.

# **Output Pulse Factor**

Increasing the output pulse width reduces the maximum frequency at which a total variable can be retransmitted. Pulses will be missed if the output cannot "keep up" with the rate of total counts. You can use the output pulse factor to ensure that this maximum is not reached.

The maximum pulse output frequency is determined by:

$$\frac{1000}{(2 \times \text{pulse width in ms})} \text{Hz}$$

The minimum pulse factor required is determined by:

For example: To calculate the required pulse factor to avoid losing counts in retransmission if a total counts at a maximum rate of 75 units/sec (Hz) and the required pulse width of a remote counter is at least 50 ms:

The maximum pulse output frequency is:  $\frac{1000}{2 \times 50} = 10$ Hz

The minimum pulse factor for that frequency is:  $\frac{75}{10} = 7.5$ 

#### **Alarms**

There are two alarm relays, in the advanced option, that can be assigned to rate variables such as volume flowrate, or set as an equipment failure alarm.

The alarm switches "on" whenever an alarm condition exists. The alarm switches "off" when the alarm condition no longer exists. However, you may need to configure external alarm devices that require acknowledgement for cancelling an alarm.

### **Equipment Failure Alarm**

Any alarm relay can be assigned as an equipment failure alarm. This alarm setting has normally closed contacts that open when the instrument displays any error message as listed in **Error Messages** on page 55, or if there is a loss of power to the instrument.

SET	$\downarrow$	igodatarrow units params inputs outputs $f ALARMS$ comms tm/log setup test end
RELAY	ALRMn	Select a rate variable to assign to the alarm relay.
		<b>Note:</b> If the alarm type is set to "equipment alarm", this relay assignment setting is ignored.
		Press • or • to select the variable that is required as an alarm.
TYPE	$FLRM_n$	The options available for alarm types are as follows:
		<ul> <li>HI-NO — High Alarm, Normally Open contacts</li> <li>HI-NC — High Alarm, Normally Closed contacts</li> <li>LO-NO — Low Alarm, Normally Open contacts</li> <li>LO-NC — Low Alarm, Normally Closed contacts</li> <li>AL-NC — Equipment Alarm, Normally Closed contacts</li> </ul> Press ▲ or ▼ to select the type of alarm required.
POINT	FILRMn	The Alarm Setpoint is available for viewing and editing only when the alarm type is a high or low alarm.  The Alarm Setpoint is the value (in engineering units of assigned variable) at which the alarm condition occurs and therefore the alarm is on.
		Each alarm is completely independent, e.g. a High alarm does NOT need to have a higher setpoint than the a Low alarm.

SET	) ↓	$igoditarrow$ units params inputs outputs $\mathbf{ALARMS}$ comms tm/log setup test end
HYST	ALRMn	The Alarm Hysteresis is available for viewing and editing only when the alarm type is a high or low alarm.
		Alarm hysteresis loops occur when the alarm toggles continuously on and off when the process variable is close to the setpoint.
		For a high alarm, the alarm activates when the value of the variable rises above the alarm setpoint and deactivates when the value falls below the alarm setpoint minus the amount of the hysteresis setting (if any). For a low alarm, the alarm activates when the value of the variable falls below the alarm setpoint and deactivates when the value rises above the alarm setpoint plus the amount of the hysteresis setting (if any).
		For example, with a high alarm setpoint of 200, and a hysteresis setting of zero, a value oscillating between 197 and 202 will cause the alarm to toggle on at 200 and toggle off below 200. However, if the hysteresis is set to 5, the value of the variable must fall below 195 to cancel the alarm. The alarm will reactivate only when the value again rises above 200.
DELAY	ALRMn	The Alarm Delay is available for viewing and editing only when the alarm type is a high or low alarm.
		The Alarm Delay is programmed in seconds and can be used to eliminate undesired alarm activation during start-up or shutdown operation.

# **Communications**

The instrument has three communication ports:

- **RS-232 Port** A 9-pin female connector on the rear panel of the instrument.
- **Infra-red Port** Located on the front panel, below the status indicators.
- **RS-485 Port** (Advanced option only) Terminals on the rear panel.

SET	) ↓	$lacktriangledown$ units params inputs ouputs alarms ${f COMMS}$ tm/log setup test end
PROTOC	R5232 R5485 INFRA	The Communications Protocol for each communication port can be set to either ASCII or Modbus RTU. A protocol cannot be assigned to more than one port at a time. If a port is not being used, set the protocol to NONE.
		If the Real Time Clock option installed the RS232 port can also be assigned the printer protocol (PRN).
		For the selected port, press or to select NONE, RTU, ASCII or PRN (RS232 only).
BAUI	R5232 R5485 INFRR	The Baud setting is the speed of the communication port in data bits per second.
		The baud rate of the instrument must match the baud rate of the communication device that the instrument is connected to.
		Use ▲ or ▼ to select 2400, 4800, 9600 or 19200 baud.
PARITY	R5232 R5485 INFRR	The Parity bit offers a small amount of error checking, to help detect data corruption that might occur during transmission.
		The parity bit setting of the instrument must match the parity bit checking of the communication device that the instrument is connected to.
		Press ▲ or ▼ to select EVEN, ODD, or NONE.
S-BITS	R5232 R5485 INFRA	The Stop bit indicates the end of a transmission. Stop bits can be 1 or 2 bit periods in length. The stop bit setting of the instrument must match the stop bit setting of the communication device that the instrument is connected to.
		Press ▲ or ▼ to select 1 or 2 stop bits.
RTU	AJJR	The Modbus RTU protocol address must be in the range of 1 to 247. When multiple instruments (slaves) are connected to one communication device (master), each assigned address must be unique.
		<b>Note:</b> The master device uses the RTU address 0 (zero) for broadcasting to all connected slave units.

SET	$\downarrow$	$lacktriangledown$ units params inputs ouputs alarms ${f COMMS}$ tm/log setup test end
ASCII	Allk	The ASCII protocol address identifies each communicating device.
		The address must be in the range of 1 to 255. When multiple instruments (slaves) are connected to one computer (master), each assigned address must be unique.
FLASH	PORT	The Flash Driver Port assignment defines the communication port for downloading software into the instrument.
		The default setting of this assignment is the RS-232 port.
		Press ▲ or ▼ to select RS-232, RS-485, or INFRA.

# **Time Settings and Data Logging**

#### **Instrument Clock**

**Note:** The real-time clock is part of the advanced option package.

The instrument has a real-time clock for recording logged events. The clock displays the time and the date. The date format can be set to European format (day/month/year) or American format (month/day/year). The time clock uses the 24-hour format.

The clock will continue to operate for up to 5 years (typically) on the internal battery if there is no power connected to the instrument. Therefore, after an interruption to the power supply, the instrument recommences normal operation although there will be no data recorded during the period without a power supply.

**Note:** If there is an interruption to the power supply and the battery has failed, the instrument displays an error message when the power supply is restored. In this case, you should set the current time and date so that the instrument continues to log data at the correct times.

#### **Data Logging**

The instrument will log a total of 1000 deliveries (batches) if the real-time clock option is installed. The logs are taken at the end of each batch or upon reset if a batch has been aborted before the preset total has been reached.

SET	) ↓	lacktriangledown units params inputs ouputs alarms comms $TM/LOG$ setup test end
DATE	FORM	Clock Date Format
		The European date format is: dd/mm/yyyy or (Day-Month).
		The American date format is: mm/dd/yyyy or (Month-Day).
		Press ▲ or ▼ to select DAY-M or M-DAY
CLOCK	YEAR	The Clock Year defines the current year for the real-time clock.
CLOCK	M-JAY	The Clock M-DAY setting defines the current month and date for the real-time clock. This parameter is programmed in Month-Day format for both European and American date formats.
CLOCK	H-MIN	The Clock H-MIN setting is the current time in hours and minutes for the real-time clock.
RESET	L065	Reset the logged data. You may need to reset (clear) the logged data if you change the time/log settings.
		Press or to select YES, then press the set key. The instrument makes three beeps to confirm the reset command.
REPORT	L065	The Printer Protocol Report Logs defines the number of latest logs to be included into a printable report.
		Enter the number of logs between 0 and 99.
REPORT	TYPE	The Printer Protocol Report Type determines the nature of the printout from the REPORT PRINT - HOLD.SET prompt in the main menu. The following report types available in this instrument are:
		• REP-10 Preset number of latest logs
		Press ▲ or ▼ to select Report Type.
PRN	TYPE	The Printer Protocol Printer Type allows the nature of the printer being used to be specified. The following printer types available in this instrument are:
		<ul> <li>PRN-01 Generic computer printer</li> <li>PRN-02 Generic roll printer (prints first line first)</li> <li>PRN-03 Slip printer TM295</li> </ul>
		Press or to select Printer Type.

# **General Setup Parameters**

SET) ↓		lacktriangledown units inputs ouputs alarms comms tm/log $f SETUP$ test end
DEFRULT	V AR	Select the main menu variable to display on power up or when the display timeout period has elapsed if it is enabled.
		Press or to select the default variable display.
SUPPLY	VOLT	The instrument provides a power-limited supply for external transducers.
		Press or to set the transducer supply voltage between 8 and 24 volts DC as required.
T-OUT	MOJE	If the Display Timeout mode is enabled, and there is no user activity for the defined timeout period, the display panel returns to the default display.
		This function is useful for the following reasons:
		<ul> <li>to return the display to a preferred variable after the user has finished reading other information,</li> <li>to cancel the calibration mode and return to the default display if the</li> </ul>
		user does not exit from the calibration mode for any reason.
		Press • or • to select the display timeout function as follows:
		• <b>DISABLE</b> - Timeout is completely disabled.
		• <b>EN DISP</b> - Timeout is enabled during Normal mode and Calibration View mode.
		<ul> <li>EN EDIT - Timeout is enabled during Calibration Set mode.</li> <li>EN ALL - Timeout is enabled for all modes.</li> </ul>
T-OUT	SEC	The Display Timeout period defines the delay for the Display Timeout mode if it is enabled.
		The display timeout period can be from 10 to 99 seconds.
RESET	ACCUM	The Reset Accumulated Totals function clears all of the accumulated totals and the non-accumulated totals.
		Press or to select YES, then press the set key. The instrument makes three beeps to confirm the reset command.

SET) ↓	$ ightarrow$ units inputs ouputs alarms comms tm/log $\operatorname{\mathbf{SETUP}}$ test end
DISPL TAGS	The Display Tags option determines whether the instrument displays the default display tags or the user-defined tags. The display tag setting also defines whether the instrument displays the default error and warning messages, or the user-defined messages.
	Note: The user-defined tags can be entered into the instrument only by the manufacturer or the distributor.  Press ▲ or ▼ to select the Display Tags option as follows:
	<ul> <li>DEFAULT - the instrument displays the default (English) tags</li> <li>USER - the instrument displays the user-defined tags.</li> </ul>
BUCK-L I-OUT	If the backlight timeout is enabled, and there is no user activity (any keys pressed) for a period of 10 seconds, the display backlight switches off to save power. The backlight switches on when a key is pressed. Select the backlight timeout mode as required.
	Press ▲ or ▼ to select ENABLE or DISABLE.

# **Test Menu**

The Test menu enables you to view the inputs and outputs to and from the instrument.

In Calibration Set mode, (by entering the system password) you can control the outputs and the alarms as described in the table below.

SET) ↓		lacktriangled $ ightarrow$ units params inputs ouputs alarms comms tm/log setup $TEST$ end
FINP1 to FINP4	units	The units are displayed according to the calibration setup for this analog input. If unused or set to Default the input is 4-20mA and displayed in mA.
LINP1 to LINP4	STATE	You can view the state of the logic inputs. If the input is an open contact or inactive it will display <b>HI</b> . If the input is a closed contact or active it will display <b>LO</b> .

SET) ↓	lacktriangled $ ightarrow$ units params inputs ouputs alarms comms tm/log setup $TEST$ end
OUT1 STAT	You can control the state of the outputs. Press the or keys to set the output state as follows:
	• <b>PROCESS</b> - the output depends on the current values of the inputs and the calculations that the instrument performs.
	For a pulse output, such as a total, the output produces a pulse train as follows:
	• <b>ON</b> - a pulse train with a pulse width as set for the particular output in the Outputs menu.
	• <b>OFF</b> - no output.
	For a 4-20mA output, such as a rate, the output is as follows:
	• HI - the output is set to 20 mA.
	• <b>LO</b> - the output is set to 4mA.
REL-1 STAT	You can control the state of the relays. Press the or keys to set the selected relay as follows:
I Van ta. ta.	<ul> <li>PROCESS - the relay condition operates according to the current batch status and the relay settings as programmed.</li> <li>OPEN - the relay output contacts are set to "open".</li> <li>CLOSED - the relay output contacts are set to "closed".</li> </ul>
ALRM3 STAT	You can control the state of the alarms. Press the ▲ or ▼ keys to set the selected alarm as follows:
	<ul> <li>PROCESS - the alarm condition operates according to the current values of the inputs and the alarm settings as programmed.</li> <li>OPEN - the alarm output contacts are set to "open".</li> <li>CLOSED - the alarm output contacts are set to "closed".</li> </ul>
SUPPL Y	You can display the actual DC output supply voltage, which may help with troubleshooting.
	If the actual supply voltage is lower than the preset value (refer to <b>General Setup Parameters</b> on page 52) it may indicate that the output is overloaded.

# **System Messages**

The instrument displays messages for defined events and fault conditions.

The manufacturer or distributor can enter user-defined text for the messages. This user-defined text is displayed, instead of the default (English) messages, when the Display Tags option in the Setup menu is set to USER.

# **Error Messages**

The system displays error messages as described in the following table:

Error Messages	Description
CPU Card Failure	There are failed components on the CPU card and technical support is required.
Power Supply is Low	The input and/or output power supply voltage is too low, ensure that: <ul><li>(a) input power supply voltage is within the specified range</li><li>(b) output power supply is not overloaded.</li></ul>
New/Failed Battery - Set Time	The real-time clock has lost the correct time because the battery has failed, or there is a new battery. Set the current time and date (in the TM/LOG menu) to clear the error message and to continue data logging at the correct times.
	<b>Note:</b> The instrument can continue operating with a failed battery, but the correct time will be lost if there are interruptions to the power supply.
No Flow Detected	The no flow condition is detected when the flow timeout expires during a delivery. There must not be a period of no flow greater than the timeout value during the delivery.
Overflow Detected	The overflow condition is detected when the flow continues longer than the timeout period after the controller has attempted to stop the flow.
Leakage Detected	The leakage condition is detected when an amount greater than the acceptable total is received without flow being initiated by the batch controller.

# **Warning Messages**

The system displays warning messages as described in the following table:

Warning Messages	Description
Value Has Been Set to Default	You have entered an invalid value for a parameter. Therefore, the instrument has set the default value.
Already Assigned to Other Port	You have tried to assign a particular protocol type to more than one serial communication port. The instrument has set the protocol to NONE.
Preset Over Limit - Max Set	You have exceeded the preset limit. The instrument will set the maximum allowed value.

# Chapter 6 Communications

# **Overview**

This chapter describes the communications between the instrument and another communicating device such as a computer or a printer. You should have relevant information about the devices to which the instrument will be connected. Some connection examples are included in this manual, however, the operation and connection of other devices is outside the scope of this manual.

#### **Hardware Interconnection**

The instrument has three communication ports:

- RS-232 port on the rear panel (DB9 female connector)
- RS-485 port on the rear panel (advanced option only)
- Infra-red port on the front panel

The appropriate interface and protocols are selected during calibration.

#### RS-232 Port

The RS-232 port provides communication between the instrument and one other device such as a host computer or a printer.

**Note:** A printer must have a serial port to be able to be directly connected to the flow computer. It is not possible to communicate directly with a printer via a parallel port.

Computers use either a DB9 or a DB25 connector, and the connections to each type are shown in Figure 15.

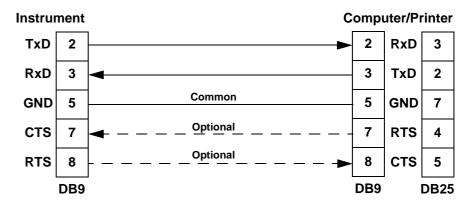


Figure 15 RS-232 Cable Connections to a Computer

**Note:** The instrument requires a cable with straight-through connections. Do not use a null modem cable for RS-232 connection to a computer.

### **RS-485 Port (Advanced Option only)**

The RS-485 port enables communication with multiple devices. Each device has a unique address so that the "master" device can communicate with specific "slave" devices.

On RS-485 links, an external terminating resistor must be connected at the furthest end of the cable. When multiple instruments are connected, they should be "daisy chained" in a multidrop configuration as shown in Figure 16. Up to 32 units can be connected to the interface at a maximum distance of 1200 metres.

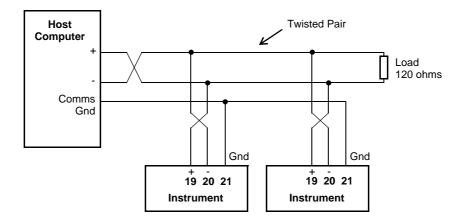


Figure 16 RS-485 Connections

#### Infra-red Port

The infra-red port is located on the front panel of the instrument. The infra-red port uses the Infra-red Developers Association (IrDA) physical layer format of signal encoding and decoding.

The nature of the infra-red port requires the communicating device to be located close to the front of the instrument. Therefore, its main use would probably be for reloading the instrument application software, or occasional collection of data, rather than continuous communications.

# **Protocols**

**Note:** ASCII and Printer protocols are only available in the "Standard" 515 CPU card, identified on the model number by: 515.xx1xxx-xxxx

Any of the ports on the instrument can use the ASCII or Modbus RTU communication protocols. The RS232 port can also be assigned the Printer Protocol.

- **ASCII** In this ASCII protocol each command and response is a string of ASCII characters. This proprietary protocol is developed by Contrec to allow for simple information interchange. The main advantages of this mode are that it allows extended time intervals to occur between characters without causing a timeout error and that messages can be sent and monitored easily with a simple ASCII terminal.
- Modbus RTU Modbus RTU is an industry-standard protocol which allows the instrument to be easily connected to computers running supervisory software systems. The main advantage of this mode is that its greater character density allows better data throughput than ASCII mode, however each message must be transmitted in a continuous stream.
- **Printer** In the Printer protocol there is a selection of printer types. Please refer to the **Printer Protocol** on page 71 for full details.

**Note:** If a port is not being used, its protocol should be set to NONE in the instrument configuration as described in **Communications** on page 48.

A protocol cannot be assigned to more than one port. Therefore if you assign Modbus RTU protocol to the RS-485 port, you cannot assign it to the RS-232 port also. The RS-232 port can now only use the ASCII or Printer protocol or NONE.

# **Simple ASCII Protocol**

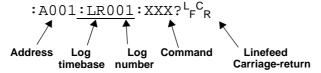
**Note:** Not all ASCII commands are applicable for Batch Controller applications.

This simple ASCII protocol requires that all requests are initiated with a colon (:) and terminated with a carriage return  $(^{C}_{R})$ . The message termination can include a linefeed before the carriage-return  $(^{L}_{F}{}^{C}_{R})$ , but it is the carriage-return that acts as the message termination.

All responses by the instrument are terminated with a linefeed and a carriage-return  $(_{F}^{C}_{R})$ .

# **Requests Format**

The format of a request to the instrument is as follows:



Each request must include the address and command portions. The underlined section is an optional part of the request string.

#### **Address**

In multipoint communications, each instrument must have a unique address and it is essential in the request for identifying a particular instrument. However, it may be set to 000, for special broadcast commands. For single-instrument communications, the address can also be set to 000 in the request.

Refer to **Communications** on page 48 for setting the instrument address.

**Note:** The instrument always responds with its address in the header regardless of the type of request.

#### Log Type and Number

The log type and number enables a communicating device to retrieve data from the instrument. The data can be from the event-based logs or from the current process variables with the either accumulated or non-accumulated (resettable) totals.

The log request is optional. If the log request is not included, or the log number is set to 000, the instrument returns the current process variables. If the log request is included, the log number defines the specific log entry by counting backwards. The most recent log entry for a timebase is 001.

The "last edit" log records the process variables at the time of the last exit from the calibration edit mode. There is only one "last edit" log, therefore, if a number is included in the request, the instrument ignores the number and returns the data at the time of the last edit. Likewise, there is only one set of current process variables with "non-accumulated totals", therefore it also ignores any log number included in that request.

The types of the logs applicable to this instrument are as follows:

Log Type
LE - last edit log
LR - logged records (non-timebased logging)
LN - current totals displayed as Non-accumulated

The number of the log entry is the same as shown on the front panel of the instrument. For example, a request for LR003 would return the data for the log entry two batches prior to the most recent batch log entry.

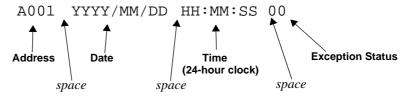
# **Instrument Responses**

The instrument response time to any enquiry is not more than 300ms. The responses from the instrument are in the following format:

The components of the response message are as follows:

#### Header

The format of the response header from the instrument is as follows:



The instrument **Exception Status** codes that the instrument returns for the ASCII protocol are the same as those described for the Modbus RTU protocol in **Instrument Exception Status** on page 68.

#### **Data**

The format of the data variables from the instrument is as follows:

		8	9	1	2	3	•	4	5	6		M	3						V	Ο	L	U	M	$\mathbf{E}$	
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	22	23	24	25	26	27
		Va	ılue	e (al	lign	ied	rig	ht)			space	Un	it (	alig	gne	d le	eft)	space	It	tem	(a	ligr	ied	left	<b>:</b> )

**Note:** The decimal point in the Value is always at character position 8. Therefore whole numbers are aligned right at the decimal point, with trailing zeroes.

#### **Variables Request**

The variables request asks the instrument to return the value of one or more requested variables. All totals are transmitted as accumulated totals.

Command	Description
:RVA?	Return all variables
:RVD?	Return the default Total and Rate
:RV0? :RV9?	Return the specific variable. The numbers relate to the position in the variables menu. For example, V0 is Energy, V1 is Power and so on.

#### **Variables Request and Response Example**

The following request is for the only instrument that is connected to the communication port to return the values of all main menu variables.

```
: A 0 0 1 : R V A ? _{F}^{C}
```

The following is an example of a hypothetical instrument response. Refer to **Main Menu Variables** on page 3 for the list of variables that would be returned for this application.

```
A 0 0 1
         2 0 0 2 / 0 3 / 1 4
                              18:25:00
                                                0 0 L<sub>F</sub> C<sub>R</sub>
           6.116
                       MWh
                                    ENERGY
         16.573
                                    POWER
                       M
     1 3 2 0 . 5 3 0
                       m 3
                                    VOLUME
         58.300
                                    V-FLOW
                      m 3 / M
     7627.117
                       ΚG
                                    MASS
       3 4 4 . 4 6 0
                      KG/M
                                    M - F L O W
       230.000
                       DEG C
                                    TEMP
           1.260
                       MPA
                                    PRESS
                                                  L<sub>F</sub> C<sub>R</sub>
           0.174 m3/KG
                                    SP-VOL
                                                  L<sub>F</sub> C<sub>R</sub>
     2886.760
                       KJ/KG
                                    SP-ENT
L<sub>F</sub> C<sub>R</sub>
```

The following message to an instrument, requests the current values for the default rate and total:

```
: A 0 0 1 : R V D ? L CR
```

The instrument response would be similar to the following:

#### Log Request

The log request asks the instrument how many logs will be included in a printed log report. These are the values described in **Time Settings and Data Logging** on page 50.

Command	Description
:RLR?	Return the number of log records (non-timebased logging)

#### **Log Response Example**

The following message asks the instrument with address 001 to return the number of hourly logs that the instrument stores:

```
: A 0 0 1 : R L R ? _{F} _{R}
```

The instrument response would be similar to the following:

#### **Clear Data Request**

The clear data request asks the instrument to clear the data in the selected registers.

Command	Description
:RCN?	Clear the non-accumulated (resettable) totals
:RCA?	Clear the accumulated totals
:RCL?	Clear the logs except for the "last edited" log

#### **Clear Data Request Example**

The following message asks the instrument with address 001 to clear the logged data that the instrument stores:

```
: A 0 0 1 : R C L ? ^{L_F} ^{C_R}
```

The instrument response would be similar to the following:

```
A 0 0 1 2 0 0 2 / 0 3 / 1 4 1 8 : 2 5 : 0 0 0 0 ^{L_F} ^{c}_R
```

#### **Instrument Information Request**

The Instrument Information request asks the instrument to return the general information about the model and version codes. The instrument exception status is returned as a part of the header as it is with the header for all command responses.

Command	Description
:RIG?	Return the general information about the instrument such as
	Model number, Application number, Version and Serial
	numbers etc. These items are returned as a block in the same
	format as shown on the display in the "Model Info" menu.

#### **Instrument Information Response Example**

The following message asks the instrument with address 001 to return the general information about the instrument:

```
: A 0 0 1 : R I G ? _{F} _{C}
```

The following is an example of a hypothetical instrument response:

```
A 0 0 1
             2 0 0 2 / 0 3 / 1 4
                                          18:25:00
5 1 5
                                    -11-F-L_FC_R
                  MODEL
S C 0 1
                                    F - T P - L_F C_R
                  INPUT
S C 0 1
                                  0\ 1\ 0\ 1\ .\ 0\ 0\ 1^{L_F} ^{C}_R
                  VERS
CUSTOM
                  VERS
                                    0\ 0\ 0\ 0\ 0\ 1\ L_F\ C_R
UNIT
                                    1 2 3 4 5 6 L CR
                  S / N
L CR
1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 |
```

### **Corrupted or Invalid Requests**

If the instrument receives a corrupted or incomplete request, there is no response. The instrument discards any partial request and waits for the next enquiry.

If the instrument receives a request message in the correct format, but for a non-existent option, it returns only the message header. For example, if the instrument received the following request variables message :A001:RVT? it will return only the header because there is no T option for the 'Variables Request' message.

#### **Modbus RTU Protocol**

Modbus RTU (remote terminal unit) is an industry standard protocol that allows the instrument to be easily interfaced to other communication devices.

The instrument implements the Modbus protocol as detailed in the *Modicon Modbus Protocol Reference Guide* PI-MBUS-300 Rev J (June 1996).

#### **Message Format**

In RTU mode, messages start with a silent interval of at least 3.5 character times. The first field transmitted is the device address. Following the last transmitted character, a similar interval of at least 3.5 character times marks the end of the message. A new message can begin after this interval. The entire message frame must be transmitted as a continuous stream. A typical message frame is shown below:

Address	Function	Data	CRC Check
1 byte	1 byte	n bytes	2 bytes

Except for broadcast messages, when a master device sends a query to a slave device, it expects a normal response. One of four possible events can occur from the master's query:

- If the slave device receives the query without a communication error, and can handle the query normally, it returns a normal response.
- If the slave does not receive the query due to a communication error, no response is returned. The master program has to process a timeout condition for the query.
- If the slave receives the query, but detects a communications error (parity or CRC), no response is returned. The master program has to process a timeout condition for the query.
- If the slave receives the query without a communication error, but cannot handle it (for example, if the request is to read a nonexistent register), the slave will return an exception response informing the master of the nature of the error.

#### **Instrument Address**

The address of the instrument is programmable in the range from 1 to 247. Some addresses are reserved according to PI-MBUS-300 and have a special meaning:

- 0 = Broadcast, no response required from slave devices
- 248 to 255 Reserved

#### **Function Codes**

The instrument accepts the following function codes:

Code	Name	Description
03	Read data register(s)	Obtain the content of one or more 2-byte data registers.
06	Preset data register	Preset one 2-byte data register.
07	Read status register	Obtain the content of 1-byte status register.
16	Preset data register(s)	Preset one or more 2-byte data registers.

#### **Exception Response**

The instrument forms an exception response by adding 80H to the function code and using an exception code as the 1-byte data field in the returned frame. Implemented exception codes are as follows:

Code	Name	Description
01	Illegal function	The function code is not a legal action for the slave.
02	Illegal data address	The data address is not a legal address for the slave.
03	Illegal data value	The data value is not a legal value for the slave.
05	Acknowledge	The slave has accepted the request and is processing it, but a long duration of time will be required to do so.
06	Slave device busy	The slave is engaged in processing a long duration program command. The master should re-transmit the message later when the slave is free.

### **List of Data Registers**

The following list describes the addresses and meaning of the data registers in the instrument. The floating point values are expressed in the engineering units that were selected for the variables when the instrument software was downloaded.

The registers are grouped in blocks that relate to a particular function of the instrument.

**Note:** Conventional numbering of registers often starts from 1, therefore be aware that "register 1" in this case has "address 0" and so on.

#### **Current and Logged Process Data**

This block of registers is available for the retrieval of current or logged process data with its matching time and date information.

Use the log timebase and log number to retrieve the logged information from the appropriate register. If a particular log number does not exist, or the instrument does not have the optional real-time clock, the time and date stamp and associated variables are set to zero.

Register	Name	Comments	Read Only or Read/Write	Type
1	Mass		R	FP*
3	Reserved		R	FP
5	Reserved		R	FP
7	Reserved		R	FP
9	Reserved	Process Variables	R	FP
11	Reserved	Trocess variables	R	FP
13	Reserved	By default totals are the Accumulated	R	FP
15	Reserved	values. If current Non-accumulated	R	FP
17	Reserved	(resettable) totals are required, set	R	FP
19	Reserved	register 37 to 06. All logged totals are	R	FP
21	Reserved	the Accumulated values.	R	FP
23	Reserved		R	FP
25	Reserved		R	FP
27	Reserved		R	FP
29	Reserved		R	FP
31	Year		R/W	Ι <sup>†</sup>
32	Month	Current Date/Time or	R/W	I
33	Date	Logged Date/Time Stamp	R/W	I
34	Hour	(see register 38 Log Number).	R/W	I
35	Minute	Only current Date/Time can be edited	R/W	I
36	Second		R	I
37	Log Type	00 - hourly or log records 01 - daily 02 - weekly 03 - monthly 04 - yearly 05 - last edit of calibration 06 -current totals are non-accumulated values, register 38 is ignored.	R/W	I
38	Log Number	If set to 0, current variables and Date/Time are retrieved	R/W	I

Register	Name		Read Only or Read/Write	Туре
39		01 - clear logs 02 - clear accumulated totals 03 - clear non-accumulated totals	W	
40	Reserved		R/W	

<sup>\*</sup> FP = Floating Point (2 registers = 4 bytes)

**Note:** The Floating Point variable is represented in IEEE-754 Floating Point 4-byte format and requires two 2-byte data registers:

IEEE-754	Modicon Registers
1st byte	low byte (register X)
2nd byte	high byte (register X)
3rd byte	low byte (register X+1)
4th byte	high byte (register X+1)

This means that two data registers must be read or written to obtain, or preset, one data value.

#### **Instrument Exception Status**

This register is available to verify the status of the instrument.

Register	Name	Comments	Read Only or Read/Write	Туре
41	Exception	00 = no error	R	I*
	Status	01 = analog input 1 failure		
		02 = analog input 2 failure		
		03 = analog input 3 failure		
		04 = analog input 4 failure		
		05 = invalid calibration parameter		
		06 = invalid reference parameter		
		07 = invalid property		
		08 to 09 reserved		
		10 = process parameters out of range		
		11 = input is over limit		
		12 = no flow error detected		
		13 = overflow error detected		
		14 = leakage error detected		
		20 = system failure		
		21 = power supply is low		
		22 = new or failed clock battery		

<sup>\*</sup> I = Integer (2 bytes) (Holding Registers)

<sup>†</sup> I = Integer (2 bytes) (Holding Registers)

## Instrument Configuration, Control and I/O

This block of registers is available in some applications to give access to important information in the instrument.

Register	Name	Comments	Read Only or Read/Write	Type
42	Parameter	0 = User	R	I*
	Source	1 = Modbus		
43	Logic Inputs	0 to 15 Binary representation of logic inputs	R	I
		B0 = 0/1 (LSB) input 1 activated/deactivated		
		B1 = 0/1 input 2 activated/deactivated		
		B2 = 0/1 input 3 activated/deactivated		
		B3 = 0/1 input 4 activated/deactivated		
44	Operation State	Representation of operation status	R	I
		0 = Reset		
		1 = Maintenance		
		2 = Completed		
		3 = Waiting to restart		
		4 = Paused		
		5 = Waiting for timeout		
		6 = Running (Slow Start)		
		7 = Running (Prestop)		
		8 = Running (Full Flow)		
45	Relay State	0 to 15 Binary representation of relay state.	R	I
		0 = open; 1 = closed.		
		B0 = relay 1 (LSB)		
		B1 = relay  2		
		B2 = relay  3		
		B3 = relay  4		
46	Relay	0 to 15 Binary representation of relay control.	R/W	I
	Control	0 = open; 1 = close.		
		<b>Note:</b> Only the general relays configurable in		
		the Alarm section of calibration are able to be		
		viewed and controlled by Modbus.		
		B0 = relay 1 (LSB)		
		B1 = relay  2		
		B2 = relay  3		
		B3 = relay 4		

Register	Name	Comments	Read Only or Read/Write	Type
47	Relay Control Source	0 to 15 Binary representation of relay control source.  0 = Local (controlled by instrument operation)  1 = RTU (controlled by Modbus register 46).  B0 = relay 1 (LSB)  B1 = relay 2  B2 = relay 3  B3 = relay 4	R/W	I
48	Reserved			
50	Control Mode	0 = Idle/LocalControl from logic inputs1 = StopSuspend current batch2 = RunResume/start batch3 = ResetClear current batch totals	R/W	Ι
51 to 99		This bank of registers gives access to the control set point values in the same order as described within <b>Parameters</b> on page 37. The accessible values are those items immediately following the parameter items that sets the access as either USER or RTU.	R if 42 = 0 R/W if 42 = 1	FP <sup>†</sup>
101	Analog Inp.1	Raw analog input data.	R	FP
103	Analog Inp.2	4-20mA inputs are read in Amperes.	R	FP
105	Analog Inp.3	0-5V or 1-5V inputs are read in Volts RTD inputs are read in degrees Kelvin.	R	FP
107	Analog Inp.4	Unused inputs are configured as 4-20mA.	R	FP

<sup>\*</sup> I = Integer (2 bytes) (Holding Registers)

† FP = Floating Point (2 register = 4 bytes)

70 515 BF04

#### **Printer Protocol**

A printer protocol is available in the 500 Series. It provides the ability to print out live data, individual logged data and to do some report-style printing of logged data. The method of printing these and the format of the printouts is described below.

**Note:** Printer output is only available if the Real Time Clock option is fitted and is only available on the RS232 communications port.

The selection of Printer Protocol can be made for the Communications Protocol options for the RS232 port. A list of log report types and printer types available at the end of the TM-LOG calibration menu.

#### **Report Types**

The list of report types is as follows:

• REP-10 Latest Logs Report

The number of logs printed in each report are determined by the values programmed for Report Logs in the TM-LOG menu.

#### **Printer Types**

The list of available printers is as follows:

- PRN-01 Generic computer printer
- PRN-02 Generic roll printer (printing first line first)
- PRN-03 Slip Printer TM295

#### **Customizing a Printout**

A customized printout can be provided which can have up to 4 header lines and 3 footer lines. It is also possible to include or exclude each main menu items on the printout. If any customizing of the printout is required discuss this with the distributor.

### **Types of Printouts**

#### **Live Data**

The RESET key, when in main menu, is shared as the PRINT key if the printer protocol has been selected. A printout will be initiated whenever this key is pressed. If printing is not required, do not select printer protocol.

The format of this printout will be:

Custom Header Line 1 Custom Header Line 2 Custom Header Line 3 Custom Header Line 4

Current Docket No.

Instrument Serial No. & Tag

Current Date & Time & Status
Variable unit value
Variable unit value
Variable unit value
etc.

Custom Footer Line 1
Custom Footer Line 2
Custom Footer Line 3
----- <separation line>

(Note that blank header and footer lines are not printed).

#### **Docket Number**

The docket number that appears on the live data printout indicates the print number. This number is cleared when the Accumulated totals are reset. If the Reset Mode is set for Delayed, where a print can be generated without resetting the non-accumulated totals, an additional number in brackets will be shown that indicates the number of prints since the last reset. i.e.

DOCKET No. 000256 (000036)

#### **Instrument Serial Number and Unit Tag**

The instrument serial number and unit tag is the same as the information shown in the Model Info menu. For more details refer to **Model Information** on page 22

#### **Individual Log Data**

When in the Log Menu and while holding the DISPLAY key to view the data of the log of interest the RESET key can be pressed to initiate a printout of that log entry. The printout will have the time and date stamp corresponding to when the log was taken. After the print has been initiated there will be the opportunity to scroll to view another log entry and print again.

Since each log entry stores the delivery totals only, the printout will not have any accumulated totals. The format of the printout with this exception is the same as the LIVE DATA printout:

#### Custom Header Lines

Instrument Serial No. & Tag

Delivery No. Date & Time & Status Variable value unit Variable unit value value Variable unit etc.

Custom Footer Lines

----- <separation line>

#### Log Report Printing

As there is the likelihood that the reports can be of a considerable length it is strongly recommended that only the 80 Column printer with Z fold (tractor feed) paper be used. This is just as much for the memory storage of printer as it is for the reliable paper supply.

There is a HOLD.SET REPORT PRINT prompt under the main menu with the ability to print the pre-selected type of report. Pressing and holding the SET key for two seconds will initiate the printout. Any of the Log Reports will have the following format:

Custom Header Lines

Variable

Variable

etc.

Title of Report <internally set, indicates report type> Current Date & Time Instrument Serial No. & Tag ----- <separation line> Delivery No. Date & Time & Status Variable unit value Variable unit value value Variable unit etc. ----- <separation line> Delivery No. Date & Time & Status Variable unit value

73 515 BF04

value

value

unit

unit

			<separation line=""></separation>
Delivery No. Dat	e & Time		
Variable	unit	value	
Variable	unit	value	
Variable	unit	value	
ETC  Custom Footer L.			<separation line=""></separation>

Reports such as "Latest Logs" will print in the historical order, and for those logs that have no data (e.g. unit was powered off at the time) the print will show "Data not available". i.e.

Del No. Date	a Not Avail	able	<separation line=""></separation>
Delivery No. D	 ate & Time		<pre><separation line=""></separation></pre>
Variable	unit	value	
Variable	unit	value	
Variable etc.	unit	value	

If the unit is programmed for 0 logs for the latest log reports then the report will only consist of the header and ID information and a "Data Not Available" message.

Custom Header Lines

Title of Report

Current Date & Time Instrument Serial No. & Tag

Data Not Available

Custom Footer Lines

----- <separation line>

#### **Printer Data Control**

Some printers have limited data buffers and are therefore unable to collect all the print data being transmitted. The 500 Series has the capability of software handshaking. The Xon/Xoff characters can be used by any of the printer types to control the flow of data to ensure that data is not lost.

Some printers will also transmit an Xoff character in response to other events such as printer being off-line, print head not engaged or power being removed. The specific behaviour of the printer being used should be noted.

#### **Error Messages**

There are two printer error messages that can be displayed.

#### **PAPER OUT**

This message is related to the Printer Type PRN-03 TM295 Slip printer. It is standard procedure with this printer to check for paper status before printing. If a print is attempted but there is no paper the PAPER OUT message will be scrolled. The instrument will continue to poll the printer for paper and if paper is detected before a communications timeout expires the print will commence.

#### **COMMS TIMEOUT**

This message is relevant for all printer types and will be activated for the following conditions.

- 1. If the flow of data is stopped due to software or hardware handshaking and is not allowed to resume before the communications timeout.
- 2. If Printer Type is PRN-03 Slip printer and a paper status is requested but no response is received within the timeout period.
- 3. Paper Out has been detected for Printer Type PRN-03 but no paper is inserted within the timeout period.

When a communications timeout error has been activated the message COMMS TIMEOUT will be scrolled once, the request to print will be cleared and the instrument will return to its normal mode.

## Appendix A Glossary

**ASCII** American Standard Code for Information Interchange. For the ASCII

protocol, the instrument receives and transmits messages in ASCII, with all command strings to the instrument terminated by a carriage return. Replies from the instrument are terminated with a line-feed and a carriage-return.

Filtering The process of suppressing oscillations or random signals in the input

signal.

**IrDA** The Infra-red Developers Association is a group of computer and software

manufactures who have agreed on a format for communication among

infrared devices.

Linear Correction A scaling of the input signal to represent the actual flow parameter.

Modbus RTU The Modbus protocol is a message structure for communications between

controllers and devices regardless of the type of network. In RTU (remote terminal unit) mode, each 8-bit byte in a message contains two 4-bit hexadecimal characters. This mode has greater character density than

ASCII and allows better data throughput than ASCII for the same baud rate.

Normalised A normalised input ranges from 0 to 1.000. For 4-20 mA input, the signal is

**Input** set to 0 at 4mA and the signal is set to 1.000 at 20mA.

Passive Output Requires an external power supply.

Signal

515 04 77

78 515 04

# Appendix B Model Numbers

## **Product Codes**

Model	Supplementary Code					Coc	le	Description
515 .		- BF04					BF04	
	1							Panel mount enclosure
	2							Field mount enclosure (not yet available)
Enclosure	3/5	3/5					Explosion proof Ex410 with metric glands (5 specifies heater version)	
	4/6							Explosion proof Ex410 with NPT glands (6 specifies heater version)
	0				_	<b>Basic</b> – 9 way DB RS232 serial port, 2 relays, 1 isolated 4-20 or pulse output and 4 logic inputs		
Output Option	ons	ns 1					Advanced- also includes RS485 port, 2 extra relays, 1 extra isolated output and Real-time clock for printer output and logging	
CPU Type         0           1         1					Original - no ASCII or printer protocol, basic logging (100 logs)			
					Standard - ASCII and printer protocol, extra logging (1000+ logs)			
	E					For 220/240 VAC		
Power Supply A				For 110/120 VAC				
				D				For DC power only 12-28 VDC
Display Panel Options F		Fully optioned (with backlight, LCD backup and Infra-Red comms port)						
C C			С		Conformal coating - required for maximum environmental operating range. Recommended to avoid damage from moisture and corrosion.			
PCB Protection N			N		None - suitable for IEC standard 654-1 Climatic Conditions up to Class B2 (Heated and/or cooled enclosed locations)			
Application Pack Number BF04							Defines the application software to be loaded into the instrument	
For example: Model No. 515.111EFC Displayed on the 500 Series as:						- 11-F-		
(only h/w that affects the operation is represented)					n is re	epres	212 MODEL	

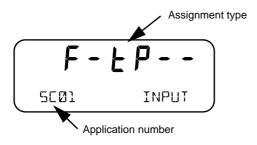
**Note:** Example full product part number is 515.111EFC-BF04 (This is the number used for placing orders).

## **Custom Version Codes**

	Code		)	Description	
	00			Factory Default Application	
	01			Contrec Pty. Ltd. Melbourne Australia	
	02			Contrec Pty. Ltd. Sydney Australia	
Origin Code	03			Contrec Europe Ltd. West Yorkshire UK	
Identifies Distributor	04	04		Contrec - USA, LLC. Pelham AL 35124 USA	
	05			Flowquip Ltd. Halifax UK	
	06				
	etc.				
		0		English (Default)	
	1 2 User Language 3			German	
				Dutch	
User Language				French	
		4		Spanish	
		5			
		etc.			
	000		000	Distributed and being Described and the Charles	
Distributor's Code 999			Distributor's own choice. Possibly a code that identifies the customer and the application.		
		999			
For example: 02 3 157			023157		
Displayed on the 500 Series as:			CUSTOM VERS		

## **Application Information Code**

The Application Information code is an aid for users and service personnel to determine the type of inputs that are used in a particular application. The Application Information code is displayed on the instrument as shown below.



The Application Information code is returned as part of a General Instrument request (as described in **Instrument Information Request** on page 64).

The Application number identifies the application as in the following examples:

- SC01 steam flow computer for frequency flow meter
- GN02 natural gas flow computer for analog flow meter

The Input Assignment type indicates the physical input that is assigned to each input on the instrument. The code is made up from six characters as follows:

FINP1	FINP2	AINP1	AINP2	AINP3	AINP4
Х	Х	Х	Х	Х	Х

The codes are as follows:

- - not used in this application
- A indicates a generic analog input such as for density or level
- d indicates a density input
- F indicates a generic flow input such as for volume or mass, (frequency or analog)
- H indicates a high flow input for stacked inputs
- L indicates a low flow input for stacked inputs
- P indicates a pressure input
- 9 indicates a quadrature input
- Ł indicates a temperature input.

For example, **F-LP--** is an instrument with FINP1 (frequency input 1) assigned to a flow input, AINP1 assigned to a temperature input and AINP2 assigned as a pressure input. The other inputs are not used.

# **Appendix C Units of Measurement**

## **Available Units of Measurement**

The following is a list of the available units of measurement used across the range of 500 Series applications.

Units Type	Available units of measurement
Volume	m <sup>3</sup> , Km <sup>3</sup> , Ltr, Gal, KGal, MGal, ft <sup>3</sup> , kft <sup>3</sup> , Mft <sup>3</sup> , bbl
Volume Flowrate	m³/s, m³/min, m³/h, m³/D, L/s, L/min, L/h, Gal/s, Gal/min, Gal/h, KGal/D, MGal/D, ft³/s, ft³/min, ft³/h, Mft³/D, bbl/s, bbl/min, bbl/h, bbl/D
Volume K-Factor	P/m³, P/Ltr, P/Gal, P/ft³, P/bbl
Mass	kg, g, Ton, lb, Klb
Mass Flowrate	kg/s, kg/min, kg/h, g/s, g/min, g/h, Ton/min, Ton/h, Ton/D, lb/s, lb/min, lb/h, Klb/min, Klb/h, Klb/D
Mass K-Factor	P/kg, P/g, P/Ton, P/lb, P/Klb
Energy	kJ, MJ, GJ, kWh, MWh, kBTU, Ton.h, therm, cal, kcal, Mcal
Power	kJ/h, MJ/h, GJ/h, kW, MW, kBT/M, kBT/h, Ton, therm/min, therm/h, kcal/h, Mcal/h
Energy K-Factor	P/kJ, P/kWh, P/kBTU, P/Ton.h, P/therm, P/kcal
Temperature	Deg K, Deg C, Deg F, Deg R
Pressure	Pa, kg/m², kg/cm², kPa, MPa, mbar, bar, psi, Atm, inH <sub>2</sub> O, mmH <sub>2</sub> O
Density	kg/m³, kg/Ltr, lb/ft³, SG60F
Specific Volume	m <sup>3</sup> /kg, L/kg, ft <sup>3</sup> /lb
Specific Enthalpy	kJ/kg, BT/lb, cal/g, cal/kg, kcal/kg, Mcal/kg
Reynolds Number	E+0, E+3, E+6 (scaling for unitless variable)
Length (Level)	m, mm, cm, INCH, FOOT
Velocity	m/s, m/M, m/h,ft/s, ft/M, ft/h
Length K-Factor	P/m, P/cm, P/INCH, P/FOOT
Area	$m^2$ , $ft^2$
Ratio	%

## Index

Numerics	C
0-5V input 9	calibration
4-20mA	menu 34
input 9	set mode 32
output 11	view mode 31
ompar ii	clock
$\mathbf{A}$	battery 50
address, instrument 60	date format 51
alarm	real-time 50
delay 48	codes
equipment failure 47	application information 80
hysteresis 48	customer version 80
relays 47	exception 68
setpoint 47	product number 79
alarms menu 47	common preset values 19
analog input	communication
connections 9	connections 13
scaling 2	protocols 59
application code 80	communications 3, 57
approvals 4	menu 48
ASCII protocol 59	connections
	communication 57
В	communications 13
back panel 8	control relays 12
batch	electrical 8
configurations 26	input 9
errors 28	output 11
operations 29	control loop
start 27	tuning 23
stop 27, 28	control modes 22
batch control 26	customer version codes 80
BATCH key 18	customizing a printout 71
batch limit 19	<b>G</b> 1
batch modes 25	D
batch preset	data log
common values 19	viewing 20
batch processes 29	date format 51
battery	default variable 17
failed 55	delay, alarm 48
life 50	digital output 11
new 55	
baud rate 49	

display	instrument
specifications 5	address 60
timeout mode 52	request format 60
timeout time 52	responses 61
DISPLAY key 18	settings 36
display-only parameter 31	interconnections, communication 57
_	interference suppression 13
E	isolated outputs 3
earthing 15	
edit batch preset 19	K
electrical connections 8	key
equipment failure alarm 47	BATCH 18
error messages 55	DISPLAY 18
exception codes 68	RESET 18
Exception Status 61	RUN 18
	SET 19
F	STOP 18
features 1	TOTAL 18
flash driver port assignment 50	keys, front panel 18
flow control	
local 22	${f L}$
loop 23	lamps, status 18
tune 23	local flow control 22
format, date 51	logged data 20
front panel 17	viewing 20
infra-red port 14	logic input connection 10
keys 18	logic input control 28
lamps 18	loop flow control 23
G	M
	main menu items 18
general specifications 5	
glossary 77	menu
Н	alarms 47 calibration 34
hardware connections 57	
hysteresis, alarm 48	comms 48
nysteresis, ararm 40	inputs 41
I	outputs 44
infra-red port 14, 48, 58	params 37
input	setup 52
0-5V 9	test 53
4-20mA 9	tm/log 50
connections 9	units 36
analog 9	messages
_	error 55
specifications 5	system 54
inputs menu 41	warning 55
installation 7	Modbus RTU protocol 65

mode	preset mode 25
display timeout 52	printer
process control 22	data control 74
set calibration 32	error messages 75
view calibration 31	protocol 71
model numbers 79	report types 71
modes, batch control 25	printer types 71
mounting 7	printouts
C	individual logs 72
N	live data 71
number	log report 73
model 79	types 71
serial 22	product number codes 79
	programmable parameters 31
0	protocol
on-off mode 25	ASCII 59
operation configurations 26	communication 59
operation, batch control 26	Modbus RTU 65
operation, control modes 22	printer 71
operation, front panel 17	pulse factor, output 46
output	pulse factor, cusput to
connections 11	R
4-20mA 11	real-time clock 50
digital 11	rear panel 8
pulse factor 46	relay
specifications 5	connection 12
outputs menu 44	relay outputs 3
	relays, alarm 47
P	release mode 25
panel	remote control 28
lamps 18	RESET key 18
mounting 7	responses, instrument 61
rear 8	RS-232 port 14, 48, 57
parameter	RS-485 port 14, 48, 58
display-only 31	RTU protocol 65
not visible 31	RUN key 18
password-protected 31	,
programmable 31	$\mathbf{S}$
parameters menu 37	scaling analog input 2
parity bits 49	serial number 22
password-protected parameter 31	SET key 19
port	setpoint, alarm 47
assignment, flash driver 50	settings
flash driver assignment 50	instrument 36
infra-red 14, 48, 58	setup menu 52
RS-232 14, 48, 57	shielding 15
RS-485 14, 48, 58	snubber 13
power supply interruption 50	specifications 5
preset batch value 19	standards 4

```
starting a batch 27
status lamps 18
stop bits 49
STOP key 18
stopping a batch 27, 28
suppression, interference 13
system
   errors 55
   messages 54
   warnings 55
T
terminal designations 8
test menu 53
timeout
   mode 52
   time 52
tm/log menu 50
TOTAL key 18
tune mode 23
tuning control loop 23
U
unit tag 22
units
   menu 36
variable, default 17
version, customer 80
view data logs 20
\mathbf{W}
warnings 55
```